

radio 3-2-1-FIRE

how BIASed are tapes?

# **ELEKTOR Artist:** the ultimate guitar preamp

Z-80 CPU Card



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Z80-A-CPU card U. Goiz and R. Mester The Z80 is one of the most popular microprocessors around, it's about time the device was mentioned in Elektor. Although the Z80-A-CPU is the heart of the control unit for the new Polyformant, it is compatible with the Elektor bus system, therefore making the Eurocard collection accessible to Z80 users.	A. Nächtmann K.S.M. Waltaven
the Elektor Artist.  It could be described as the ultimate in versatility for the electric guitar. It could be described as the ultimate in versatility for the electric guitar. It could be described by the provides a tolar flow inputs in the versatility of the provides at part of four input site into two channels; extensive tone controls; built-in reverb and fuzz, with a large number of 'loop' switching facilities, giving the musician something at a reasonable cost which can only be found on more expensive equipment. We feel sure the Artist will satisfy constructors and discerning musicians alike.	
prop. tachometer	. 5-39 ELEKTOR Artist

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A rev-counter for model aeroplanes. This design bridges the gap between the differing worlds of electronics and balsa wood. When matching a particular propeller to an engine a reliable method for measuring the rpm is extremely useful. The circuit described is straightforward in construction.

Not just a clock but a sophisticated housekeeper based on the 6502 micro-

processor. It can be used to control a multitude of household appliances, such as cookers, lighting, alarms, central heating. Set it weeks in advance and go on holiday without a care in the world. 5-51 RAM/EPROM card for the Z80 .....

A. Seul In principle the RAM/EPROM card (Elektor September 80) can be used with a variety of systems. Just a 'cut and shunt' exercise with no additional components is required to interface this card to the Z80 and more importantly to the Z80-A-CPU, as introduced elsewhere in this issue.

software cruncher and puncher ...... An unusual title perhaps, but one which succeeds in describing in as few words as possible what this article is about: a disassembler and EPROM programmer for the Junior Computer.

5-57 market ...



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5-10 — elektor may 1982 advertisement



5-12 – elektor may 1982 selektor



## Photographing the hidden beauty of microchips

Manchester photographer Ad Sternberg is a man fascinated by the delicacy, beauty and colour of microchips. Combining highly sophisticated photographic and engineering techniques he has developed a unique method of photographing in fine detail and enlarging in full colour the integrated circuitry — invisible to little larger in diameter than the dot on a typewriter.

a typewriter.

According to Mr. Sternberg, scientists and engineers in electronics have performed wonders in reducing them to a microcosm. A great deal of science and engineering skill is needed in photomicrography not only to produce a detailed negative image for enlargement but also enhanced and with controllable colour contrast.

Colour print examples of Mr. Sternberg's work in the photomicrography of microcircuits — enlarged possibly 400 times are now on display and used by internationally-known companies such as Plessey, Standard Telecommunications, International Computers, National Semi-conductor and Ferranti Electronics. Conductor and Ferranti Electronics developed with special regard to photography of microcircuits up to 8 mm (0.3 inches) diagonal, using a diffraction limited system.

Camels may not be able to go through the eye of a needle, microchips — which



Photo 1. Ad Sternberg using a microscope to select a chip for photography.



Photo 2. A typical Ferranti small integrated circuit photographed and enlarged by Ad Sternberg.

today provide the circuitry used in comnuters space craft rocket missiles telecommunications and more humble objects such as cookers and washing machines - certainly can. Absolute cleanliness is vital. The tiniest particles of dust would produce big black blobs. Mr. Sternberg has been interested in photography since teenage. He joined an industrial and commercial photographic business in 1947, having previously spent some years learning to work to fine tolerances in an engineering tool factory. When silicon chips - microchips - arrived on the industrial scene in the 1960s he was approached by Ferranti who asked if he could, at reasonable cost, improve on the quality of the results they were getting themselves with colour photographs of silicon chips, wanted for publicity, record and internal company purposes. The biggest 'chips' were six millimetres square - others being much smaller.

Taking up the challenge, Mr. Sternberg found himself immersed in a year's experimentation and research. Little photographic material existed for this type of work, nor was there ready-made equipment. But, combining his photographic and engineering knowledge, he combed photographic, scientific instrument and second-hand shops for 'bits and pieces, and gradually designed his own equipment and techniques and colour processing methods.

A way of increasing the colour contrast had to be found. The colours in the microchips are very weak by the time they pass through the microscope optics. Correct lightning was a great proper to the colour control of the colour colours of the colo

The chips have become more complex,

of course, over the years. They pack more and more on one chip. Nowadays. computers have to be used to design the circuits because they are too complicated for even the finest scientists without computer aid. They have thousands of transistors and resistors on them. Mr. Sternberg believes, with good reason. that his equipment, methods and experience in this unusual field make his work unique - and that the techniques developed are applicable to photomicrography and photomacrography in general. Of course he realises there are other people in this field, particularly in the United States, However, it calls for quite a blend of different expertise not only in photography but also in engineering optics and illumination - and dedication over a long period - to produce relatively low-cost results.



Photo 3. A Ferranti F100L microprocessor chip, containing approximately 10,000 transistors in the eye of a needle. The chip is about 1/5-inch square.

#### Telecults Norwalk, Connecticut

The Maharaia Pampkin Bolanee has announced the formation of his Ethereal Television Network (ETV), marking the first of the so-called cultist organisations to enter the cable broadcasting industry. Claiming his programs will be patterned after those produced by the Christian Broadcasting Network, the Venerable One stated that the shows will attempt to 'cast light on the darkened corners of the cosmos, bringing peace and harmony to those seeking the Ultimate Truth and Karma'. The 146-year old mohatma said that ETV can currently be seen by 43.000 homes across the country and will be broadcast via the Comstar D-2 satellite thirty-six hours per week.

Outlandish, you say? Perhaps, but not at all unlikely. According to a recent article in VideoPrint, it's just a matter of time!

IRD Inc. USA



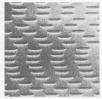
#### LaserVision in the UK

Philips intend to launch its LaserVision Disc system onto the UK market towards the end of May this year.

To start with, players and discs will be on sale in greater London and the surrounding home countries through a restricted number of outlets. These will include high street multiples, independent retailers and specialist rental companies. Philips plan to progressively increase the number of outlets into other major cities in the UK united at the earliest opportunity.

The first catalogue will contain more than 100 disc titles of which at least 75 will be in the shops by May. The remaining catalogue titles will become available shortly afterwards. Further new releases will substantially expand the catalogue by the end of the year. Seven top programme distributors will cate from the initial catalogue, including feature films, general entertainment programmes, musicals, sport and children's albudy.

A strong advertising and promotional campaign has been set up with the intention of communicating the Laser-Vision message in an accurate and straightforward manner so that it may be understood at all levels of trade and by the consumers. LaserVision is a new and unique source of home entertainment and information for all the family. The easy-to-operate, damage-proof design of the player and the durable quality of the toughocated discs allow the equipment to be used by everyone, even children.



Not only is Phillips committed to developing the consumer market, but the company plans to enter the non-domestic market as well, as this offers considerable scope for the interactive application of LaserVision on the industrial, commercial and educational level.

(766 S)

#### 250 kW Wind turbine

The need for alternative energy resources is not only a favourte discussion topic, but is at last leading to concrete results. Which of the elements (sun, see or wind) is suitable for grown on the local climate. Not surprisingly, solar energy can be found in abundance in deesrts like the Sahara or in Arizona. Unfortunately, the British Isles do not have much sun to offer, but they are visited (and sometimes plaqued) inexhaustible source of fuel.

Wind energy projects are starting to be developed on an increasingly large scale, one of the most ambitious schemes to date being the wind turbine generator designed by the Wind Energy Group for

installation on Orkney. The Wind Energy Group comprises British Aerospace Dynamics Group, GEC Energy Systems Limited and Taylor Woodrow Construction Limited. The company has signed an agreement with the North of Scotland Hydro-Electric Board to contruct the most powerful wind turbine generator ever built in the Uniformation of Hill Orkney. Sto be erected on Burgar Hill, Orkney.

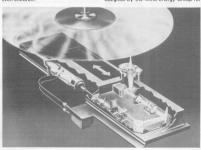
The 20 m diameter turbine has a rated nower of 250 kilowatts (kW) at 17 metres/second (m/s) wind speed and a rotational speed of 88 revolutions/minute (rev/min). It will begin to operate at a wind speed of 8 m/s and shut down when wind speeds exceed 27 m/s. It has an estimated annual energy output of 700,000 kilowatt-hours (kWh). The machine is to have a synchronous generator variable pitch rotor blade tips and a soft power transmission arrangement. Provision is being made for the machine to run in both fixed speed and variable speed modes. The rotor will be mounted to the main shaft with what is known as a teetering hub. This arrangement reduces the forces and moments on the blades and supporting structure.

The machine will be the first in the UK to in recent times to be connected to an isolated diesel-electric grid system, and with a power rating of 250 kW will be the most powerful turbine to be connected in such a way anywhere in the world. These factors made its in economic and technical evaluation especially relevant to many hundreds of similar grid systems elsewhere in the world who are burdened with large enerating cost.

The Group has paid particular attention to this potential market in designing the transmission and control system of the machine to achieve power quality acceptable to a small diesel grid system. The prototype will allow for tests to evaluate fixed versus teetering hubs. constant versus variable speed operation. as well as a wide range of operational strategies. The machine is to be extensively monitored under a contract with the Department of Energy using a computer based data acquisition system which will scan sensors placed on the machine to measure performance, forces and displacements.

Procurement of components is now taking place prior to assembly and ground testing of the nacelle and rotor in the last quarter of 1982, while construction of the foundation and tower will begin in the summer. Commissioning and first synchronisation of the machine is schedules for the first quarter of 1983.

The 250 kW machine also acts as the prototype for the larger machine which will be 60 m in diameter. When complete the project will be the largest demonstration in the UK of an alternative energy technology.



Certain cassette and reel-to-reel tape decks and recorders are equipped with such an array of meters and switches that some look as though they were intended for aircraft cockpits rather than for home use. Although noise reduction and equalisation circuits are necessary, the factor which contributes more than anything else to the quality of recordings is the correct application of 'BIAS'. In order to set the 'bias' correctly and therefore match recorder to tape, a signal generator, as described in this article is required. Arred with such a generator, readers are able to improve on the quality of recordings and use whatever tape type they wish.

# test tone generator



# how to set the 'BIAS' on your tape recorder

The existing range of decks and tapes is enormous. In an attempt to get over some of the confusion and conflicting assels literature, manufactures tend to specify which type of tape will get the best performance out of their decks. This is fine, but no consideration is given in many cases to when the user can no longer afford, or get hold of the type of tape specified. Normally very little information is contained in the operating manual about altering the bias' setting, or even where to find the control.

Nearly all decks have equalisation circuits so that the record/playback signal reaching the preamplifier stage of a 'Hi Fi' system is as 'flat' as possible. Without such circuits the playback response would exhibit pronounced bass and treble losses. These losses are partly due to tape speed and type, but the bias also plays an important role. A correct 'bias' setting is needed to achieve a good recording level for all frequencies across the audio spectrum. This will in turn allow high playback output, low distortion, and a reasonably 'flat' response. Unfortunately there is a different ideal 'bias' setting for each frequency. The setting for a mid-frequency tone

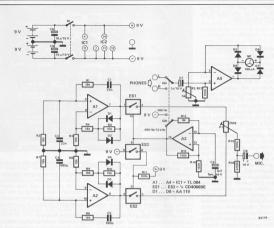


Figure 1. The circuit diagram of the complete tone generator and a suitable power supply circuit. Readers are advised to use 'Veroboard' as the construction medium.

(400 Hz) is quite different from the one required for a 13 kHz signal. Generally speaking, the higher the frequency the lower the 'bias' level. Therefore tape deck manufacturers specify the type of dape to use and choose a 'bias' setting (out of necessity) which is a compromise. A real in depth study of 'bias' is certainly not practical at this stage, as it would probably take up most of this issue. Anyway, we are more interested in practice than in theory.

#### Tone generator

As outlined above a test tone generator supplying a mid and low frequency signal is necessary. Figure 1 shows the circuit diagram of the generator. It mainly consists of two bridge oscillators. The first one, arranged around A1, produces a practically distortion-free sine wave signal of 400 Hz. Stabilisation is achieved by using germanium diodes. The second oscillator (constructed around A2) operates in the same way, but produces a 13 kHz signal. Both signals are fed in turn to the outstage by means of the CMOS



switches ES1 and ES2. The circuit around A3 functions as a square wave generator with a frequency of about 0.25 Hz, activating the electronic switches in such a way that the output will alternate between 400 Hz and 13 kHz every two seconds.

With a positive pulse, ESI and ES3 are closed and the 400 Hz signal reaches the output. With a negative going pulse ESI and ES3 are open and ES2 is closed allowing the 13 kHz signal to be fed to the output. Present P1 ensure the output amplitude for each signal is the same. The network made up of R15, R16 and C6, in the output stage, sets the impedance and level of output so that it can be fed directly to the 'mike' input of the deck.

The fourth opamp Ad is used to drive a Blevel meter for monitoring purposes. A moving coil instrument or a multimeter set to the 100 µA range is sufficient. Preset P2 sets the gain of Ad, With the help of S2 the signal taken from the headphone socket of the deck can be monitored, one channel at a time. By switching over S2b the square wave generator is by-passed and only the 400 Hz signal reaches the output. Two completely separate switches can

be used for S2a and S2b, A single double-pole one was only used in the prototype for convenience.

#### Checking and calibrating the test tone generator

Feed the output from the generator to both input channels of the tape deck. Turn the recording level controls of the deck to zero. If the deck has volume controls affecting the output level to the phones then turn these to zero as well. Centre P1 and P2, and switch on both the recorder and the generator. S2b is positioned to give a fixed 400 Hz signal. Now turn up the recording level controls until a reading of 0 dB appears on the 'vu' meters. Position S2b to activate the square wave generator part of the circuit. The frequency of the signal supplied to the recorder will fluctuate between 400 Hz and 13 kHz every two seconds. Rotate P1 until a balanced amplitude level for both frequencies is achieved, in other words, until the reading on the deck recording level meters is the same for both frequencies. With some recorders an amplitude drop will occur for the higher frequency, Should this happen then adjust P1 until the difference between the two readings is minimal (say 0 dB at 400 Hz and -3 dB at 13 kHz). Whatever the readings, take a note of them as they will come in handy later

on Set the recording levels of the recorder to -20 dB and adjust P2 to give a monitor reading of 0 dB.



#### Using the generator

Before going any further the following points should be kept in mind. Before adjusting the 'bias' give the

generator time to warm up. Any procedures undertaken should be

AMPEX

repeated several times in order to achieve reliable results.

Tape heads, etc. should be de-magnetised and cleaned.

Insert a tape or cassette into the recorder, and record the 400 Hz and 13 kHz signals at a level of -20 dB and a monitor meter reading of 0 dB. Switch to playback and monitor the signals again for each channel and note if they are the same as the recorded ones. These should be approximately 0 dB or as

previously noted (0 and -3 dB). Any deviation in readings will mean that the 'bias' setting will have to be altered. Therefore change this setting and repeat the procedures until the correct readings appear. The 'bias' setting will now be correct for the particular tape in use

To set the 'Dolby' frequency roll-off level, first record only the 400 Hz tone.

after first disconnecting the monitoring circuit. It is advisable to check the manufacturer's instructions concerning the 'Dolby' settings before continuing. Switch to playback and note whether the playback level readings on the deck meters are the same as when the signals were recorded. If they are not then the

'Dolby' preset or control will have to be adjusted until they are. That should now complete the procedures necessary to interface with the

#### Practical hints

particular tape in question.

Readers are reminded that the lower priced reel-to-reel and cassette recorders do not have an external 'bias' control. The lucky ones with middle and upmarket models will certainly have these. making calibration far easier. For the unlucky ones it is best to consult a circuit diagram or other data in order to locate the presets inside the recorder. The 400 Hz tone is also very useful as a 'bench-mark' in the calibration of 'equalisation' and other audio circuits.



# polyphonic synthesiser

U. Götz and R. Mester

## the digital keyboard assembly and debounce circuitry

The general principles and basic theory behind the new Elektor polyphonic synthesiser were introduced in the March 1982 issue. However, this article is devoted to the practical side, namely the constructional details, thereby enabling readers to commence building. We start of fw with the debounce circuitry for the keyboard contacts and the input unit (together with its bus board) which acts as the keyboard interface for the main CPU card.

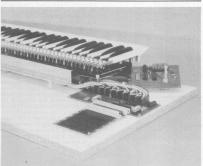


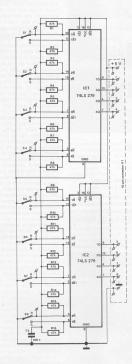
Photo 1. This photo shows how the debounce unit, the input unit, the tune-shift unit and the bus board are mounted and wired.

The digital keyboard design caters for up to five octaves (61 keys). Although it is obviously possible to use fewer keys, the relatively small price difference between three and five octave keyboards prompted the designers to go for the latter. This also means that the range of musical possibilities can be exploited to the full. The keyboard contact blocks, or switches, are mounted on eight individual printed circuit boards in seven groups of eight and one group of four. Each board also contains the debounce circuitry for its respective keys. The contact blocks used are the (gold wire) single pole GJ type from Kimber Allen. The debounce circuitry for each key consists of an RS flipflop. There are ten connections between each printed circuit board and the input unit. 8 for the debounce circuitry and 2 for the power By now readers will have noticed that

only half of the eighth printed circuit board is used, meaning that only 60 of the 61 keys can be used (see figure 8). A close examination of the debounce circuitry in figure 1 and the printed circuit board layouts in figures 5, 6 and 7 should provide a clue, however. Effectively, the 8 printed circuit boards are identical. The 8 keys on each board are subdivided into two groups of four. The reason for this is that the design had to fulfil the main conditions of optimum performance and value for money, while being simple to construct. In reality, the keys at the extreme ends of the keyboard are very rarely used anyway. If readers wish to use the lower key rather than the higher one, all that needs to be done is to shift the connections down one key (or semitone). This does not present too much of a problem, since the VCOs of the individual channels can be adjusted to give the required pitch. If all 61 keys are to be used, then the 8th printed circuit board will have to be fully utilised. This does mean, however, that the printed circuit board assemblies would protrude from the side of the keyboard, making it more difficult to fit the unit into a case. To make construction easier and for space considerations, we suggest that the last board is cut in two and the unused half discarded (see figure 8). This means, of course, that the relevant connections on the input board will have to be grounded. In practice, this is accomplished by earthing the four respective pins on the ten-pin connector. If this was not carried out, the processor would be confused into thinking that the non-existing keys were permanently depressed!

#### Mechanical construction

The keyboard contact blocks are mounted on the underside of the board (see figure 3). Position the blocks (notch side towards the board) on the printed circuit board and glue them into place. A good strong adhesive such as Araldite



Key contacts: Kimber-Allen Typ GJ

82105-1

should be used. The adhesive should be applied sparingly taking care not to get any near the contact wires. Bend the short wires at the rear of the blocks towards the board and solder them into place. It is important to remember that the contact blocks must be wired so that the circuit is closed when the key is depressed.

The next step is to drill a hole in a convenient place near the centre of each printed circuit board. This hole should be large enough to allow a self-tapping screw and the blade of a screwdriver to pass through it. The reason for this is so that the carrier board can be mounted directly to the keyboard chassis (this is explained later on).

All the other components, including the 10 pin connector, are then mounted to the boards. The 8 (17% actually) boards are now ready to be assembled on to the carrier board, by means of suitable nuts, bolts and spacers. The length of the height of the contact blocks, which is approximately 9,5 mm with the types specified.

The carrier board is then attached to the keyboard chassis. The spacing between the chassis is the spacing between the chassis is the chassis is often the chassis is often in 'fishplate' form (see figure 2) so as to allow the centre contact spring to be located in one of the holes. It is essential that the centre contact spring touches the upper contact when the key is depressed.

Most keyboard chassis' are not predrilled, therefore readers must decide for themselves where the carrier board is to be attached. Self-tapping screws are ideal for this operation, which brings us back to the holes previously drilled in the centre of the printed circuit boards. The latter will help to stabilise the construction considerably.

Exact dimensions and sizes for the carrier board, case and so on cannot be given, as these will depend on the type of keyboard used.

### Testing the debounce circuitry

The debounce circuitry can be tested quite simply. The two power supply connections on the 10 pin connector (of one printed circuit board) are linked to +5V and ground respectively. When a key is released, the voltage at the be zero volts. This should rise to +5V when the key is depressed, If all is well the keyboard can be put to one side for the time being. Take care not to damage the contact wires, since they are very fragile and will bend very easily.

#### Input unit

The input unit shown in figure 3 consists basically of an 8 bit data bus over which the processor is able to read in

1

Figure 2. Exploded view of the keyboard mechanism and the debourse circutry. The contact blocks are Availated to the underside of the debourse are Availated to the underside of the debourse are Availated to the mounted on a Carrior' board.

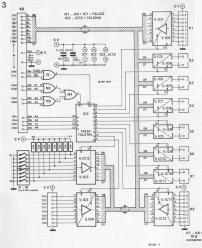


Figure 3. The circuit diagram of the input unit.

data (by means of multiplexing) via the buffer stages, IC3... IC12. The outputs of these buffers are held in a high impedance state until such time as the devices are enabled by means of the signal presented to pins 1 and 19.

Address lines AB... A7 originate from the microprocessor and are decoded via gates N1... N4 and IC2 to produce the select signals for the data buffers. This means that only one data buffer will be enabled at a time and the processor will always 'know' exactly which one is being addressed.

As the data and address lines are common to both the input and the output units, the input data will have to be disabled when the output unit is being accessed. This is accomplished by gating the RD and IORO signals from the microprocessor and feeding the resultant signal to one of the select inputs of IC2.

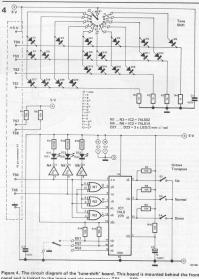
The construction of digital data processing systems can be kept simple and small, by using a common highway for multiple data transfer (this is a typical procedure in computer systems). It is interesting to know what the data presented to the microprocessor looks like. The inputs of the majority of the buffer ICs are connected to the outputs of the debounce circuitry. The processor scans the buffer ICs one by one by means of the chip enable inputs (pins 1 and 19) so that it can determine exactly which, if any, key is being depressed. The buffer consisting of half of IC3 and

half of IC12 is used by the microprocessor to determine the number of VCOs which are available in the synthesiser. As mentioned previously, any

number of VCOs between 2 and 10 can be incorporated. The eight DIL switches, S1... S8 are used to preset this number according to the information given in table 1

The connections TS1...TS8 lead to the 'tune-shift' board, which is shown in figure 4. A diode matrix ensures that the correct logic levels are presented to the data bus when switch S1 is operated. In this way the VCO frequencies can be transposed by one octave, one semitone at a time. Three pushbutton switches, S2...S4, connected to the tune-shift circuit determine the 'direction' in which the notes are shifted. The logic levels required by the system software are presented to the data bus via connections TS5 and TS6. Of the four possible set/reset latches contained in IC1, only three are used to effectively 'decode' the state of the three switches (latches 1, 2 and 4). Under normal conditions, S3 will have been depressed and the output of the first latch (1Q) will be high whereas the outputs of the other two (2Q and 4Q) will be low. Now, if S2 is depressed, the output of the second latch (2Q) will go high and the other two latches will be reset via gates N2 and N3. Similarly, if S4 is depressed, output 4Q goes high and latches 1 and 2 are reset via gates N1 and N2. Gates N1 and N3 are used to reset latches 2 and 4 when switch S3 is depressed. The current 'state of affairs' is indicated by the three LEDs (D21...D23) connected to the latch outputs via inverters N4 . . . N6. These LEDs are mounted inside the switches. The remaining latch in IC1 (latch 3) may be used in the future for expanding

the keyboard. The CPU card and the output unit with its corresponding digital-to-analogue (D/A) conversion system will be described in subsequent articles.



panel and is linked to the input unit via connections TS1 . . . TS8.

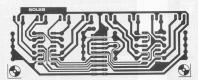
#### Table 1

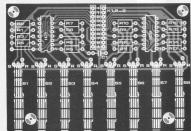
The coding for switches \$1 \$8

Table 2

The coding for switches \$1 S8: Switches \$1 \$4 (bits bd b7) represent the number of available oscillators in binary. Switch \$5 (bit 4) indicates the presence/absence of the preset facility. For the time being, switches \$6 \$8 (bits b5 b7) are ignored by the processor.						Coding of	the	data	at th	ie tu	ne-sl	hift .	outp	ut:					
switch number	SB	S7	S6	SS	S4	53	S2	S1		bit value:	b7	b6	b5	b4	ь3	b2	b1	bØ	
bit value:	6.7	b6	40	b4	b3	h2	b1	bØ					0	0	X	X	×	×	-1 octave
Dit value.	07	DB	DO	D4			-						0	1	×	×	×	×	0 octave
					0	0	0	0	not valid				1	0	X	×	×	×	+1 octave
					0	0	0	- 1	not valid				1	1	×	×	×	×	not valid
					0	0	1	0	2 VCOs				X	×	0	0	0	0	0 semi-tone
					0	0	1	1	3 VCOs				×	×	0	0	0	1	+1 semi-tone
					0	1	0	0	4 VCOs				×	X	0	0	1	0	+2 semi-tone
					0	1	0	1	5 VCOs				×	×	0	0	1	1	+3 semi-tone
					0	1	1	0	6 VCOs				x	×	0	1	0	0	+4 semi-tone
					0	1	1	1	7 VCOs				x	x	0	1	0	1	+5 semi-tone
					1	0	0	0	8 VCOs				×	x	0	1	1	0	+6 semi-tone
					1	0	0	1	9 VCOs				×	×	0	1	1	1	+7 semi-tone
					1	0	1	0	10 VCOs				×	×	1	0	0	0	+8 semi-tone
					1	0	1	1	not valid				х	x	1	0	0	1	+9 semi-tone
					1	1	0	0	not valid				×	×	1	0	1	0	+10 semi-tone
					1	1	0	- 1	not valid				×	×	1	0	1	1	+11 semi-tone
					-1	1	1	0	not valid				×	×	1	1	0	0	not valid
					1	1	1	1	not valid				×	×	1	1	0	1	not valid
				0	×	×	×	×	with preset				x	x	1	1	1	0	not valid
					×	×	×	×	without preset				×	×					not valid









Resistors:

R1 . . . R16 = 47 k

Capacitors:

C1 = 100 n ceramic or MKT

Semiconductors: IC1 IC2 = 74LS279

Miscellaneous: 8 key contacts (Kimber Allen (gold wire)/

type GJ/single pole) 10 pin plug (Molex male E 3022-10A) 10 pin socket (Molex female E 3071-10) 10 crimp terminals (Molex 4809 CL) Note: all of the above are required eight times

#### Parts list for figures 3 and 6

Resistors

R1...R10=10k

C1 = 10 µ/6.3 V tantalum

C2... C4 = 100 n ceramic or MKT

Semiconductors: IC1 = 74LS32

IC2 = 74LS154

IC3...IC12 = 74LS244

Miscellaneous:

S1 . . . S8 = 2 x 4 way DIL switches 9 ten-pin plugs and sockets and crimp terminals (see parts list for

the debounce unit) angled 2 x 32 way plug (DIN 41612)

#### Parts list for figures 4 and 7

Resistors:

R1.R2 = 1 k R5 . . . R10,R14,R15 = 10 k

R11...R13 = 470 Ω

Capacitors: C1,C2 = 100 n ceramic or MKT  $C3 = 1 \mu/6.3 \text{ V}$  tantalum

Semiconductors: D1 . . . D20 = 1N4148

D21 . . . D23 = 3 mm red LED (in digitast switches S2 . . . S4)

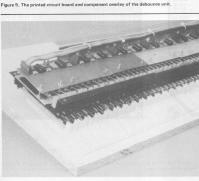
IC1 = 74LS279 IC2 = 74LS02

IC3 = 74LS14

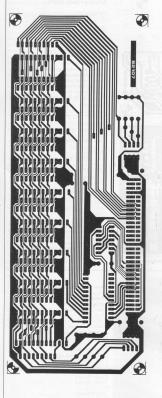
Miscellaneous:

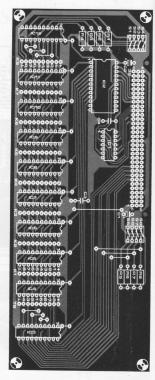
S1 = single pole 12 way rotary switch S2 . . . S4 = digitast (with LEDs)

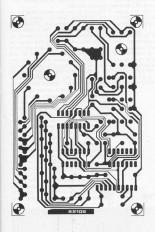
10 way plug, socket and crimp terminals (see parts list for debounce unit)



6







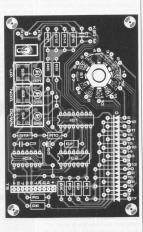
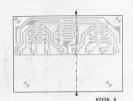


Figure 7. The printed circuit board and component overlay of the 'tune-shift' unit.

8



The system has been designed such that the existing Elektor bus board (EPS number 80024) can be used to link the CPU card and the input/output units. A suitable method of mounting the various parts of the system are shown in the photographs.

Figure 8. A section of figure 5 showing where the 8th debounce board can be sawn in two without damaging the copper tracks.

The design is based on the MW receiver circuit which was published in March 1981. This circuit lends itself very well to miniaturisation because it requires very few components and the power consumption (0.3 mA) is sufficiently low to allow the use of a small mercury.

The Ferranti ZN414 IC is the 'heart' of the circuit. This IC is reasonably well known by now, its 3 pin housing containing a straight through receiver. The only external components required are the tuning capacitor and aerial. Figure 1 shows a block diagram of the IC; a high impedance input stage, an RF amplifier, an AM detector and an AGC (automatic

gain control). Readers wishing to know more about the inner workings of the ZN 414 are referred to the March 1981 issue of Elektor.

Figure 2a shows the circuit diagram of the complete receiver, when a high resistance (approximately 200 Ω) magnetic earpiece is used. The simplicity of construction is more akin to crystal set design than anything else. The resistance of the earpiece is very important, since this controls the gain of the IC and therefore the output volume. An earpiece with an internal resistance (not to be confused with impedance) of around 200  $\Omega$  is ideal, but types having a lower resistance (within reason) can also be used, together with a resistor (Rx) connected in series. Readers should take note not to use too high a value for Rx. otherwise the output will be rather poor. Obviously the sensitivity of the earpiece will also have a bearing. The absolute minimum resistance (Rx + earpiece) is about  $100 \,\Omega$  with the maximum being 1k5, A good compromise is about 500  $\Omega$ . The prototype actually used an earpiece of 170  $\Omega$ together with a resistor of 330  $\Omega$ . If the value of Rx is high, then the connection of an electrolytic capacitor, in parallel (not more than 10 µF) should improve the output level. The actual value is not critical and will depend on the Rx/earpiece combination, Basically readers are invited to find the com-

# miniature MW receiver

a matchbox radio to set the world on fire . . . ?

Over the past fifty years a lot of miniature radio circuits have been designed. Unfortunately most of them have suffered from a lack of output power and sensitivity. Furthermore the majority always had problems with the aerial. Readers may remember the wrist watch type radios that came to the fore some time ago, when an aerial had to be wound around the wrist or in the strap. Anyway, very few of them gave a worthwhile performance With the advent of the ZN 414, designs became simpler and better. Using this well-proven chip, the article introduces a straightforward circuit with very few components which can outperform many equivalent commercially produced sets. It has good output power, reception and selectivity.



1 ZN 414 CAC CAA

Figure 1. The block diagram of the interior of the ZN 414. This tiny IC forms the basis of the matchbox receiver.

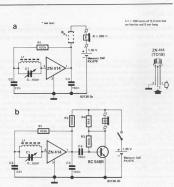


Figure 2. The basic circuit (a) uses a high impedance magnetic earpiece. An output stage is required if a crystal earpiece is to be used (b).

hination applicable to their needs, as it really depends on what output level is required.

Unfortunately the frequently used 8  $\Omega$ type is not suitable as it requires the addition of a matching transformer. A high impedance crystal earpiece on the other hand, requires an additional output stage, as shown in figure 2b. The power consumption in both circuits (2a & 2b) is practically the same, because the additional stage (figure 2b) only adds an extra 0.1 mA drain on the battery.

A decoupling capacitor for the power supply is not required, since the internal resistance of the mercury cell is extremely low.

Construction The choice of housing is left to the reader as it will depend on the size of the components. The prototype was inserted into a matchbox (see photo) simply as a guide-line and to give an impression of its relatively small size. The original design has a flat ferrite rod, 50 mm in length with a cross-section of 12 x 4 mm, but any rod approximately 10 mm in diameter will suffice. The aerial coil is made up of 100 turns of 0.2 mm enamelled copper wire, wound onto a paper or cardboard former. The ferrite rod is inserted into it. The variable capacitor is one of the twinganged variety (141 pF and 59 pF) commonly used by manufacturers in commercially available medium wave pocket radios. Should readers wish to have a lower number of windings or use a ferrite rod with an unusual permeability factor, they are advised to connect both gangs in parallel.

As everyone will agree, to design a printed circuit board for this radio would be futile, as that would probably take up more space than the complete

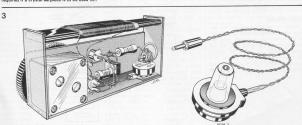


Figure 3. The construction of the matchbox radio is illustrated here. The 'chassis' is made from plastic sheet and fits inside a matchbox. There is plenty of room for all the components including the output stage if required.



radio. It is more convenient to interconnect the components directly. Figure 3 shows one method for this.

The 'chassis' is made of plastic having the same dimensions as the 'tray' of a matchbox. The variable capacitor is mounted onto the chassis by means of appropriate screws. The ferrite rod is attached by glueing each end to the sides of the chassis.

A standard earphone socket is used. Normally the which part acts to isolate the loudspeaker, but in this case it is tuilised as a battery connection. The moving contact part of the switch is cut off with pilers or a wire cutter to leave only the fixed terminal. This serves as the positive contact for the battery. A better to the positive contact for the battery, a contact for the positive contact for the serves as the negative of the chassis serves as the negative contact. The position of the socket is determined by the size (width) of the battery.

Note that an on/off switch is not necessary when constructing the circuit as in figure 2a. The supply is automatically switched on when the earpiece is plugged in. However, the circuit as in figure 2b does require a switch.

The battery should be a mercury type cell such as a 'Mallory' supplying 1.35 V

#### Final remarks

A whine or whistle heard in the earpiece when tuning between stations can be eliminated by swapping over the connections to the aerial coil. Normal mercury cells are able to deliver 200 mAh, so each cell should give between 400 and 500 hours of listening pleasure.

# the Junior Computer as a frequency counter

G. Sullivan

Microprocessor systems are often regarded as mathematical wizards, so the Junior Computer's aptitude as a frequency counter will come as no surprise...

As the name suggests a 'frequency counter' records a recurrent series of events. This does not necessarily have to be anything to do with electronics. The merry month of May, for instance, (and any other month, for that matter) has a frequency of one sunset every 24 hours (although it is not often seen in the British Isles). To take an electronic polarity one hundred times per second, this is referred to as a frequency of 50 Hz.

The point is, by what criteria is frequency measured? In the second example the number of polarity changes (from positive to negative, or vice versa) that occur during one second are simply counted. When a microprocessor is

'hired' to do the calculation work, a program consecutively displays the contents of three display buffers, in other words the last frequency to be measured. The program is interrupted either once the one second measuring time has passed, or the AC voltage has gone low. A new program is now run to check the cause of the interrupt. If a zero-crossing was involved, the period counter is incremented by one. But if the measuring time (1 second) has passed, the contents of the counter memory locations are copied into the display buffers. At the same time, a new measuring period begins. At the end of the process, a return is made to the main routine, after which the

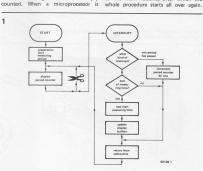


Figure 1. A series of interrupts (IRQ) are required for frequency measurement

THITTER LIMITH SOO

STA IRQH

STA EDETC LDAIM \$10 (1610)

JSR SCANDS

JUP LOOP

TXA

PHA

PHA

BPL ADD

TROSRV PHA

STAZ ACCUL

STAZ ACCUM

STAZ ACCUR

LUATE TROSPY

LDAIM IRQBRV/256

LDAIM \$3D (61<sub>10</sub>)

CNTH

RDFLAG

CNTH

LDAZ TIMEL

negg come

BNE EVIT

TOWTH SAS

LDYIM SØG

STAZ INH.X

STYZ ACCUL,X

RDT. STORE

T.DAZ TIMEH

STAZ COUNT

T.DAZ ACCUIT

STAZ ACCUL

LDAZ ACCUM

STAZ ACCUM

LDAZ ACCUH

STAZ ACCUH

ADOTH SEE

CLD

ADOTH SOO

ADCIM \$Ø1

STORE 'LDAZ ACCUL'X

DEX

BNE EXIT

SED

STA TROT.

STAZ TIMER

STAZ COUNT

STAZ TIMEL

\$1400 A9 00

\$1AØ2 85 DØ

\$1AØ4 85 D1

\$1466 85 D2

\$1AØ8 A9 29

STAND A9 TA

STAGA SD TE 1A

\$1AØF 8D 7F 1A

\$1A12 8D E6 1A

\$1A15 A9 1Ø \$1417 85 D4

\$1419 85 DR

\$1A1B A9 3D

\$1A1D 85 D5

\$1A22 58 \$1A23 20 8E 1D LOOP

81429 48

STAZA BA

\$1A2B 48

\$1A2C 98 \$1A2D 48

STATE SD FF TA

\$1A26 4C 25 1A

\$1A2E 20 D5 1A

\$1A35 8D FF 1A

\$1A31 1Ø 10

\$1A33 A5 D5

\$1A38 G6 D3

\$1A3A DØ 28

\$1A30 A2 Ø2

\$1A3E AØ ØØ

\$1A4Ø B5 DØ

\$1A42 95 F9

\$1844 94 DØ

\$1447 10 F7

\$1A49 A5 D4

\$1A4B 85 D3

\$144D DØ 15

\$1451 A5 DØ

\$1A53 69 Ø1

\$1A55 85 Dg

\$1A57 A5 D1

\$1A59 69 ØØ

\$1A5D A5 D2

\$145F 69 ØØ

\$1A61 85 D2

\$1A63 D8

\$1A65 A8

\$1A67 AA

\$1468 68

\$1469 40

STARF PR

\$1A5Ø 18

\$1446 CA

2

N1.N2 = 1/3 IC1 = 4049

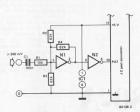


Figure 2. This circuit is added to the Junior Computer to effect the program in figure 1.

The events are depicted in the flow chart in figure 1.

A certain amount of hardware is also needed and this is shown in figure 2. This circuit is connected to the port connector of the Junior Computer to allow the frequency data to be entered into the computer. A significant negative zero-crossing in the input signal will pull port line PA7 low. The program makes sure this is accompanied by an IRQ.

The software is provided in the table. The start address of the program is \$1A00. When data is written into location EDETC, PA7 is pulled low thereby enabling an IRQ. Preparations include defining the IRQ jump vector at the start address of the IRQSRV interrupt routine, starting the interval timer (CNTH, in other words, an IRQ is enabled after every 1024 clock pulses) and storing the contents of location COUNT, Then the program LOOP is run until an IRQ takes place.

As soon as any type of IRQ is detected, the IRQSRV program is run. After saving the A, X and Y contents (used during SCANDS) on the stack, the computer examines the N flag. If N, or rather the timer flag, is zero, the IRQ cannot have been enabled by a time out. This means that it must have been caused by a change in logic level on PA7. A new AC voltage period has passed and so the computer proceeds to label ADD. The 24-bit BCD number (ACCUH, ACCUM, ACCUL - the period counter in figure 1) is incremented by one. After restoring A. X and Y (EXIT) and executing an RTI, the computer returns to LOOF

Supposing the IRQ was caused by a time out in the interval timer. The timer is started afresh and the contents of COUNT are decremented by one. Provided COUNT has not yet reached zero, a jump will be made to EXIT. If, however, COUNT is in fact zero, the STORE section is run. The measuring period has now passed and the display buffers, POINTH, POINTL and INH are assigned values equal to those of ACCUH, ACCUM and ACCUL, respectively.

So much for the program, let's put everything into practice. Connect the circuit in figure 2 to the port connector, enter the program on the keyboard (or even better, read it in from cassette) and start it via the main JC keyboard. (The main JC keyboard must be used, so as to provide the I/O definition for SCANDS.) The highest frequency that can be measured is about 10 kHz. At low frequencies greater accuracy may be obtained by extending the measuring time to 10 seconds (load AØ instead of 10 into TIMEH, address \$1A16). The result on display will of course have to be divided by ten to give the correct frequency.

Literature: Chapter 6 of the Junior Computer Book II.



ADDITIONAL ZERO PAGE LOCATIONS SØØD1 SØØD2

COUNT SØØDE TIMEH \$00D4

\$ØØD5

Table 1. The frequency counter program.

Considering the amount of brain power stored away inside the Z80-A, the CPU card circuit is surprisingly straightforward. As can be seen from figure 1 all that is needed to make the brain tick is a handful of ICs. Memory is organised according to the Elektor systems' page structure, in other words, it consists of 4K blocks. The first block (0000 ... 0FFF) is located on the CPU board and contains 2K of EPROM (0000 ... 07FF) and 2K of RAM (0800 . . . 0FFF). This particular board was designed for use with the new polyphonic synthesiser or Polyformant and the combination is described in detail elsewhere in this issue. Since only 1K

formant requires a Z80-A (MK 3880 - 4) CPU.
Essentially, the operating speed of the

processor mainly determines the time it takes to execute a program. In the Polyformant, the CPU must scan the keyboard and in the extended version it must also scan all the presets. Furthermore, it must pass on all the relevant data to the Polyformant modules (VCOs, VCFs and so on).

How much time these processes take depends on the response speed of the microcomputer. This is particularly important when the keyboard is being scanned. The faster the scan, the sconer a VCO will be able to react to a depressed key. Using the software package developed for the Polyformant, a VCO can respond within two or three milli-sconds. This delay is far too short to be

# Z80-A CPU card

### . , for the Polyformant

As the Z80 is still one of the most popular microprocessors around, it is high time the device was mentioned in Elektor. However, that is not the only motive behind this article, for the Z80-A CPU is the heart of the control circuitry for the new Elektor synthesiser. The board is compatible with the Elektor microprocessor bus system, so that the Eurocard collection will now be accessible to Z80 users.

IC18 and IC19 (see figure 1) may be omitted.

It is not absolutely necessary to position

It is not assolutely necessary to position the memory. ICs and their corresponding address decoders on the CPU board. Large amounts of software can best be stored on a separate (EP)ROM board, such as the Elektor RAM/EPROM card (ESS 80120). One or two minor modifications to the latter are required first, however, details of which are provided elsewhere in this issue.

of RAM is required in this application

#### **Buffers**

Any self-respecting CPU board will of course have to be properly buffered, as the CPU outputs are unable to drive a complete system directly. Since the buffers used here (IC9...IC13) are tri-state and are enabled by the BUSAK signal, the DMA, or multiprocessing, facility of the Z80 is retained.

#### Speed

The processor is driven by a 4 MHz crystal oscillator. This is the highest possible clock frequency for a Z80-A or MK 3880-4 CPU. With the standard Z80 or MK 3880 the clock frequency should not exceed 2.5 MHz. It should be mentioned at this stage that the Poly-

#### Wait cycles

The use of a high clock frequency automatically calls for corresponding processing speeds, or access times. The access time of a standard 2716 EPROM (IC15) will usually be too long for it to be addressed by the CPU. As for data entry, even less time is available for writing to the RAMs (IC16 . . . IC19)! There are two ways in which this problem can be solved. The first method involves the use of high-speed memory devices, that is to say, EPROMs and RAMs with an access time of 350 ns and 250 ns, respectively. The latter are easily obtainable nowadays, but 350 ns EPROMs are a little harder to find. Strictly speaking, even 350 ns is 'cutting it a bit fine', although a shortcut may be taken by implementing the OE (output enable) input instead of the CE (chip enable) input. This enables a 350 ns 2716 to be used without the

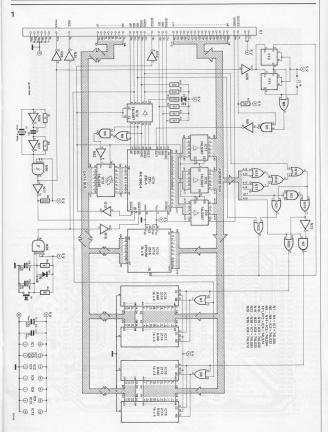
The other alternative is to slow down the CPU and use normal 'Iowspeed' EPROMs. This is done by adding wait cycles to read operations. A wait cycle lasts exactly one clock period, that is, 250 ns. The addition of a single wait cycle will therefore extend the EPROM access time to 500 ns, which gives plenty of leeway to even the most 'sluggish' types. The delay is effected by including flipflops FF1 and FF2 in the circuit.

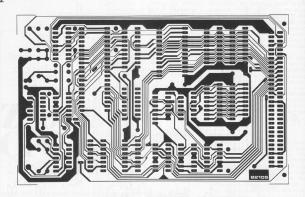
need for any special measures

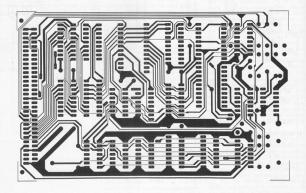
The flipflops are only active while the EPROM (CES) is being afteresed (th.D. In the EPROM (CES) is being afteresed (th.D. In the EPROM (CES) is being afteresed (th.D. In the EPROM (CES) is being aftered (th.D. In the EPROM (CES) is variable, in which case a wire link, J.I. must be included instead of Ic4. This deactivates the delay circuit. When testing the CPU, however, readers are advised to carry out the first method initially and include a wait cycle, so as to be absolutely sure that a slow EPROM will not complicate matter.

Any external memory or peripheral devices are also able to generate wait cycles by way of the WAITEX input.

U. Götz and R. Mester







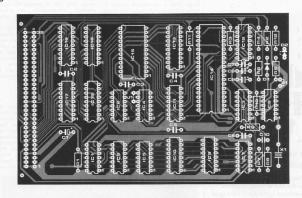


Figure 3. The component overlay for the Z80-A CPU card

Parts List

#### Resistors:

R1 . . . R6 = 4k7 R7,R8 = 1 k R9 = 330 Ω

R10,R11 = 6k8 R12 = 470 Ω

#### Capacitors:

C1,C8 = 22 µ/6.3 V tantalum C2 . . . C7 = 100 n ceramic or MKH C9 = 10 µ/6.3 V tantalum

### C10 = 10 n MKH

Semiconductors: D1 = 1N4148

D2 = LED

IC1 = 74LS00

IC2,IC5,IC6 = 75LS32

IC3,IC7 = 74LS04 IC4 = 74LS74

IC8 = 74LS13 IC9 . . . IC12 = 74LS367

IC13 = 74LS245

IC13 = 74LS245 IC14 = Z80-A (or MK 3880 - 4)

IC15 = 2716/2516

IC16 . . . IC19 = 2114-Z or 2114A-5 (access time 250 ns)

#### Miscellaneous:

S1 = push button switch

X1 = 4 MHz crystal K1 = 64-pin connector

#### Reset

Reset circuitry is needed to initialise the CPU. When the power supply is switched on, R6, C8 and D1 hold the reset input of the CPU low for a while via N29 and N10. This is the PWCI. signal and serves to reset any other boards connected to the system bus. An external reset facility has been to place S1 out of reach to prevent it from being inadverently depressed thus causing valuable information to be irrevocably lost.

#### The printed circuit board

Apart from \$1, all the components in figure 1 are mounted on a Eurocard sized, double-sided, plated-through printed circuit board. This is shown in figure 2. As the pin assignment of the 64-pin connector corresponds to that of the Elektor bus system, the board may be used in combination with a number of existing cards.

The components should be mounted on the CPU card with due care, because in some places on the board the copper tracks are so close to each other that soldering may easily cause a 'short'. Although the board is provided with a solder mask to reduce this sort of problem, a great deal of care is still required.

#### Further information on the Z80

Enough has been written about the 280 to fill an entire library. Plenty of software is available too, but users must be well-informed of the requirements of their particular system. Often the software is a software in the software is a system. Often the software is software in the software is a special article is only in the software is a special article is devoted to its use with the synthesiser. A brief description of the software is a special article in the software in the software is a special article in the software in the software is a special article in the software in the software is a special article in the software in the software is a special article in the software in

application possibility out of thousands. The advantage of using the board in a different system is that the hardware can be adapted to existing software packages. Such modifications are usually left up to the user, but nine times out of ten it is much easier to rearrange computer circuitry than to rewrite programs.

Elsewhere in this issue an article describes how to modify the 8K RAM + 8K EPROM card for use with the Z80 and therefore how readers can create their 'own' computer system.

# the Elektor Artist

## a versatile electric guitar preamplifier

This preamplifier is a companion to the 100 W power amplifier published in the April 1982 issue of Elektor. Two independent channels are provided each with two inputs. Features include high and low impedance inputs. extensive tone controls, built-in reverb and fuzz and effect 'loop' switching, providing the musician with all the extras normally found on the more expensive equipment at a reasonable price. Although originally designed for the guitarist, it can of course, be used with any other electronic instrument such as an organ or synthesiser.

Designing a really good circuit for a guitar preamplifier was quite a challenge. After a considerable number of requests from Elektor readers our design staff set about creating the Artist. The primary objective was to produce a preamplifier that satisfied a discerning musician while still remaining a practical proposition for home construction All the Artist's effects are combined onto a single printed circuit board, thereby simplifying construction considerably, The advantages of the switching modes will be obvious to the adventurous musician. This facility is something that musicians are always looking for, but rarely finding in commercial equipment, with the possible exception of HH. The front panel layout in figure 4 is a

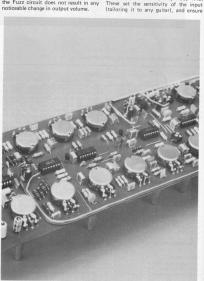
The front panel layout in figure 4 is a good point from which to start describing the circuit and facilities. It is basically a twin channel preamplifier having a low and high input. Channel I includes a five band graphic type tone control circuit, built-in Fuzz and Reverb. The amount of distortion can be fully controlled and ranges from a 'clean' to extremely 'dirty' sound. By-passing the Fuzz circuit does not result in any noticeable change in output volume.

Channel II has a simpler parametric type of tone control and reverb. The reverb 'loop' can be patched into both channels, independently or simultaneously. The Fuzz circuit is only available on channel I.

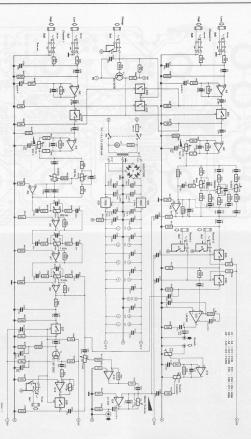
A switch enables an input to be fed to either of the two channels. This allowed the player to preset both channels and switch from one to the other at will. In the change facility as well as the change facility as well as the controlled by means of foot switches. Finally, input volume controls and a master upont volume potentioneter complete the circuit.

#### The circuit

Figure 1 shows the circuit diagram of the 'Artist'. CMOS analogue switches have been used instead of FET power transistors. This helps to keep the overall cost down without impairing cuality. The input signal from sockets Ba5... Ba8 is fed to the non-inverting inputs of Al and A3 (ICI, via the input signal from sockets and the control of the control

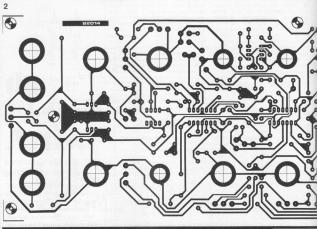


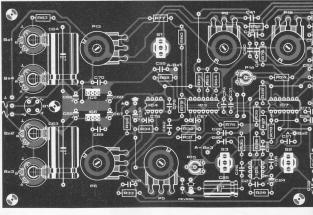
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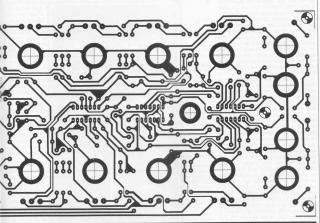


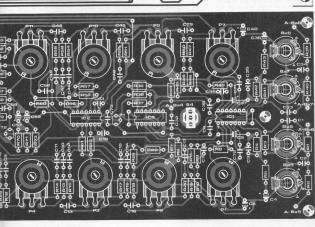


the Elektor Artist









that an input level of 7.5 mV is available to A1 and A3, irrespective of whether a high (less than 40 mV) or low (less than 10 mV) input signal is applied. The low noise opamp IC1 (A1, A3), amplifies this signal by a factor of 22, in order to achieve an excellent signal-tonoise ratio right from the start. The amplified signal (around 170 mV) is fed to either channel by means of CMOS switches ES1 . . . ES4. S4 (channel change) is used for this purpose. A foot switch connected to the Ba4 socket bypasses S4 to allow remote control.

A close look at the circuit diagram in figure 1 shows that the input signal is switched around the different parts of the circuit by means of CMOS switches. The use of this method results in noiseless switching and good channel separation. The operating voltage of IC6 and IC7 is also reduced to about half (± 8 V) their normal level, thereby reducing distortion. Potentiometers P1 and P7 set the input signal levels for channel I and II respectively. Opamp A2 in channel II is followed by the tone control circuit configured around A8. As readers will see this type of tone control network is practically standard and is common in all sorts of audio equipment. A4 in channel I is followed by a 5 band graphic equaliser giving ± 15 dB of cut and boost at 100 Hz, 300 Hz, 1 kHz, 3 kHz and 10 kHz. This is made up of a normal cut and boost tone circuit controlled by P8 and P9, and then by three band-pass filters around A6, A7

Switches S2 and S3 control ES5 and



When mounting onto metal front panel the use of plastic collar type sockets is recommended.

### **Technical Specifications**

frequency range:	40 Hz 25 kH
S/N ratio:	60 dB
noise factor:	0.1%
maximum output voltage:	4 V <sub>rms</sub>
nominal output voltage:	1 V <sub>rms</sub>
low input sensitivity:	10 mV
high input sensitivity:	40 mV
input impedance:	50 k
output impedance:	500 Ω
tone control channel I:	
treble (10 kHz)	± 10 dB
middle (1 kHz)	± 8 dB
bass (100 Hz)	± 10 dB
tone control channel II:	
10 kHz	± 10 dB
3 kHz	± 15 dB
1 kHz	± 15 dB
300 Hz	± 15 dB
100 Hz	± 12 dB
reverb output voltage:	1 V <sub>rms</sub> 4 V <sub>rn</sub>
fuzz threshold:	1.5 V <sub>rms</sub>

ES6 allowing either, or both channels to be 'patched' into the reverb loop. Once again the connection of foot switches to sockets Ba2 and Ba3 allows remote control of this facility. Opamp IC5 is the preamp for the reverb spring line. This is a standard ordinary amplifier which has been used in many other Elektor circuits. The gain of IC5 is set by R29 and C24. Obviously by changing these values IC5 can be altered to cater for the sensitivity of any particular spring line unit. With values as shown in figure 1 the output signal level from IC5 is about 4 V, making it ideal for the well-known 'Hammond' spring line, which has an impedance of approximately 8 \, \Omega\$. The output level from the spring to A11, is set by P15, in order to provide the reverb circuit with unity gain. Calibration is quite easy, P15 should be set to give the same voltage at pin 8 of A11 as that of pin 3 of ES5. Bear in mind that without connecting a reverb spring line this procedure is not possible. The reverb intensity control (P5) mixes the 'flat' and 'contoured' signal.

The Fuzz circuit around the FET T2, is a little more complicated. T2 is made to operate at a drain source voltage level of around 500 mV, in other words, near to its pinching characteristic. As the FET is driven without feedback, the level of distortion at its output is dependent on the amplitude of the input signal. Increasing the input to channel I (P7) will provide a progressive increase in distortion, giving a tone reminiscent of valve amplifiers. Just as a matter of

#### Parts list

Resistors: R1,R39 = 56 k R2 R40 = 15 k R3,R8,R21,R22,R41,R49,R70,R76 = 220 k R4.R24.R26.R28.R34.R37.R42.R68.R74.

B75 B79 B81 = 47 k R5,R14,R31,R43,R66,R72 = 2k2 R6.R9.R27.R33.R44.R46.R69 = 33 k B7 B45 = 12 k

R10,R47 = 3k3 R11,R48 = 1 k R12 R13 = 4k7

R15,R16,R18,R19 = 5k6 R17,R20,R71 = 22 k R23 = 27 k

R25,R32,R35,R38,R77,R80,R82 = 100 k B29\* = 470 Ω R30 = 10 Ω

R36,R50,R51 = 10 k R52 = 680 Ω R53,R56,R57,R60,R61,R64,R65,

R67 = 150 k R54.R55.R58.R59.R62.R63 = 8k2

R73 = 18 k R78 = 10 M R83 = 100 Ω P1,P7 = 47 k logarithmic P2.P3.P4 = 47 k linear P5 P13 = 10 k linear P6 = 100 k log. P8 = 22 k line

P9,P10,P11,P12 = 100 k linear P14 = 100 k preset P15 = 22 k preset Capacitors:

C1,C6,C33,C38,C56 = 33 n C2 C34 C78 = 47 p C3,C7,C35,C39,C43 = 100 p C4,C8,C36,C40,C57,C59 = 2µ2/16 V C5,C37 = 1 µ/16 V C9,C10,C11,C20,C21,C22,C32,C55, C58 = 10 n

C12,C14,C26,C29,C32,C54,C60,C62 = 47 n C13.C48 = 1n5 C15,C53 = 22 n

C16,C79 = 15 n C17.C28 = 220 n C18 = 22 p C19.C31.C44.C46.C61,C69 . . . C77 = 100 n C23 = 3n3

C24\* = 10 µ/10 V tantalum C25 = 100 µ/16 V C27 = 1 nC30 = 10 u/16 V C41,C42,C50,C52 = 4n7

C45 = 5n6

C47 C49 = 27 n

C51 = 470 p C63,C64 = 1000 µ/25 V C65,C66 = 1  $\mu$ /25 V tantalum C67,C68 = 4µ7/16 V tantalum

Semiconductors:

B1 = B40C1000 bridge rectifier

(round version)

T1 = BC 547B T2 = BF 256C, BF 245C IC1 = XR 4136, RC 4136

IC2,IC3 = TL 074, TL 084 IC4 = LF 355, LF 356

IC5 = LM 386 IC6,IC7 = 4066 IC8 = 7808

IC9 = 7908

Miscellaneous: S1 . . . S4 = sp on/off switch (for single hole) S5 = dp mains switch

Ba1 . . . Ba8 = 1/4 in mono lack with switch Tr1 = 2 x 12 V/200 mA mains transformer La1 = mains LED indicator

F1 = 100 mA MT fuse with fuse holder reverb spring line (Watford Electronics)

\* = see text

4

interest, an input signal of 1.5 V would completely overdrive the FET and Cripping' would result, just like any normal harmonic generator. As with the reverb circuit, P13 (Fuzz intensity) mixes the flat and distorted signals. The Fuzz 10op circuit has unity gain (set by P14), in other words, no change in volume when the Fuzz is the Fuzz independent of the Fuzz independent of

(IC4) by way of the summing resistors R24, R33, R79, and the capacitors C29, C32, C62. The (master volume) P6 controls the overall output level. The symmetrical power supply circuit uses two voltage regulators IC8 and

#### Setting up

IC9.

This merely involves the setting of the two presets P14 and P15, which is easily done by using a multimeter set to 5 V AC. Calibration is not critical, an accuracy of ± 5% is sufficient.

A nominal signal is fed to one of the inputs of channel I (10 mV low, 40 mV high). If your signal generator is not provided with a meter, measure the voltage at pin 10 of A3 (IC1), and divide by 20. This will give a good indication of the input voltage level. Now set the wipers of all the equalisation potentiometers to their centre point, Rotate P7 until 1 V is measured at pin 1 of A9 (IC3). P15 is also set to give a reading of 1 V at pin 8 of A11 (IC2). The same procedure is repeated for channel II (do not forget to connect the reverb spring line), only this time P14 is turned up until 1 V is at pin 14 of A12 (IC3).

#### The printed circuit board

Almost all the electronic components and hardware are mounted on one single board, making construction simple and straightforward. The lack of normal wiring helps to keep noise and the possibility of mistakes down to a minimum. Even the wiring to the switches/sockets should present no problem as they only conduct DC voltages.

For the sake of economy no provision has been made for the mounting of the mains transformer and spring line onto the printed circuit board. Even so, readers will find no difficulties in connecting them up. Screened cable should be used for this purpose.

#### Construction

Standard (% ins) mono jack sockets are used throughout mounted directly onto the front panel. Keep the connection wires as short as possible and use the plastic collar type of jack sockets, in order to avoid earth loops. A suitable front panel design is shown in figure 2. When using a metal front panel, care of the potentiometer spindles, toggle switches come into contact with it,



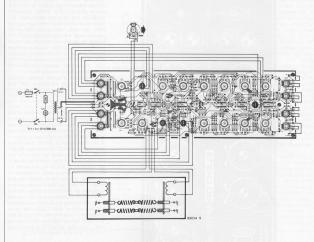


Figure 5. This clearly shows all connections to the p.c. board.



otherwise unnecessary noise is generated. This is specially important when considering the sockets, since the ground of the input has a different potential to the ground of the footswitch sockets. One good idea (as already adviced) is to use plastic spindled potentiometers and insulated sockets. It is left to the reader to decide whether to leave the sockets on the board or not. Finally don't forget about the kind of power amplifier you are going to use. In principle, the Elektor Artist can be used with any. But please, bear in mind that it will not overcome all the shortcomings of some amplifier and speaker systems around.

H

As aeromodellers will know, it is necessary to match a particular propeller with any given engine. Each propeller has a specification, indicating the optimum efficiency relative to its 'speed' (rpm). Therefore a way of measuring its speed is essential. When an engine is being tuned it is also very useful to be able to check the rom relative to any adjustwould prove costly and rather complicated to make. The only sure way to achieve a high standard with a relatively low cost is to use an electronic circuit. The speed of the propeller can be determined with the aid of opto-electronics. An analogue indication can be provided by means of a moving coil meter or, if digital is preferred, by using a digital display. Which method used will determine the cost.

### The circuit

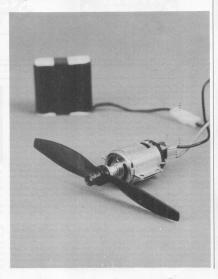
The most straightforward part of the circuit is the power supply. For convenience and mobility a 9V battery is utilised. The power consumption is surprisingly low.

The signal from the photo diode or -transistor D1, is amplified by opamp ment made. A mechanical method A1, With the turning 'prop' in front of the diode the amount of light falling on D1 will be fluctuating in direct proportion to the speed of the engine. It is advisable to place a dark-coloured 'prop' against a light background and a light 'prop' against a dark background. Diodes are included in the feedback loop of A1 to ensure that its gain will be logarithmic to compensate for changes in ambient light levels. R1 is also included to stabilise A1 when very little

# prop tachometer

a rev counter for model aeroplanes

Modellers tend to be rather slow in getting into electronics. This could stem from the fact that halsa wood and electronics are quite a few worlds apart, so that modellers may question their own skill with a soldering iron. Expertise and reliability are certainly important factors where model aircraft are concerned, as any errors are inevitably costly. However, for certain applications. like the one described here, the simplicity of construction together with the help of a ready made printed circuit board, achieves a high reliability factor.



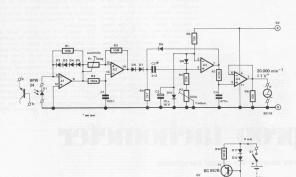


Figure 1. The circuit diagram for the tachometer. Note that a different output voltage range can be obtained by selecting a different value for C2; P2 is used for actual calibration.

A1 . . . A4 = IC1 = μA 324 D2 . . . D12 = DUS

light reaches the diode. If the circuit is only to be used outdoors, the diode can be replaced by a photo transistor connected as a diode (base and emitter only). This transistor is not as sensitive as the diode, but it will work reliably in normal daylight. It is strongly recommended that even when using the circuit indoors, readers should rely on daylight or a torch rather than on room lighting, as this could influence the accuracy of the circuit. The 100 Hz fluctuations tend to confuse the meter. Opamp A2 acts as a comparator and Schmitt trigger, converting the signals from A1 into square wave pulses for the frequency-to-voltage converter circuit around A3. The sensitivity of this stage is adjusted by P1, with the highest sensitivity at the lowest setting. In other words, the lower the switching threshold (P1 → 0), the higher the sensitivity,

The frequency-to-voltage converter circuit may look complicated, but it is actually quite straightforward. Basically it is a monostable multivibrator (monoflop) triggered by the pulses from the Schmitt trigger A.E. Each pulse is differentiated by C2, R5 and P2. The output

detected by A2.

which implies that smaller signals will be

of opamp A3 will go high' when the pulse at its non-inverting input reaches the same value as that of its rethes the same value as that of its rethes the value of the control of the value of va

The remaining components in this part of the circuit ensure that the output pulse of A3 is proportional to its input pulse and the time it takes C2 to charge and discharge. The charge level of capacitor C4 will now be determined by the frequency of the pulses from the output of A3, since they are of fixed towards and the compositional to the frequency of the changing light on the photo diode, (the input to the tachometer), and therefore the engine speed.

In the final stage opamp A4 acts as a buffer on the 10k load (R8). The output will then be within a DC range of 0 . . . 1 V.

Photo 1 shows the characteristics of the tachometer. The horizontal axis indicates the number of revolutions with the vertical axis denoting the voltage. As



Photo 1. The output characteristic of the tachometer. The horizontal scale is 100 Hz (300 rpm) per division; the vertical is 200 mV/div.

can be seen, a good linear relationship exists between the two.

#### Practical hints

Figure 2 shows the track layout for the printed circuit board. The battery can be attached to the board, if desired, by means of double-sided adhesive tape. It is strongly advised that the photo transistor (or diode) is mounted in some



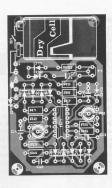


Figure 2. The track pattern and component overlay of the printed circuit board for the prop tachometer. The board has been designed to fit in a plast case from Vero (202-21028J) or West Hyde (BOC 430). Since consumption is very low the battery will last quite a long while. In this case, it may be advisable to secure it with a piece of double-sided sticky tape.

#### Parts list

Resistors:

R1,R3 = 10 M

R2 = 180 k

R4 = 2k7

R5 = 22 k

R6,R8 = 10 k

R7 = 470 k R9 = 8k2

R10 = 120 Ω P1,P2 = 100 k presets

Capacitors: C1 = 100 n C2 = 2n2\* C3.C5 = 10 µ/16 V

C4 = 470 n

The same

Semiconductors: D1 = BPW 34 (Electrovalue) or phototransistor

D2...D12= DUS D13 = BZY 6V8 400 mW

T1 = BC 557B IC1 = LM 324

Miscellaneous: S1 = single pole on/off switch 9 V battery form of protective 'handle' since it is known that fingers coming into contact with a prop turning at 15,000 rpm cause a sharp decrease in interest in all things concerned with aero modelling. Keep the connection wires between the diode and the circuit as short as possible.

#### Calibration

Setting up the circuit is very straightforward requiring the adjustment of only one potentiometer (P2). Connect a multimeter to the output, switch the circuit on and measure the offset voltage. Take careful note of this reading as it will be required later.

A normal fluorescent light tube can now be used as a calibration source. This is ideal because the light output varies in a 100 Hz rythm (twice the mains frequency). This is equivalent to 6000 pulses-per-minute, or 3000 rews of a normal twin-blade propellor! Point the photo-diode at the lamp and adjust potentiometer P2 to give a reading on the multimeter of 150 mV DC plus the offset voltage, (the previously obtained reading). That it, as far as calibration is concerned. The sensitivity is adjusted by means of P1, when measuring the rews

of a propeller. Obviously this setting will depend on the distance between the propeller and the diode or transistor, as well as on the contrast between propeller blades and background.

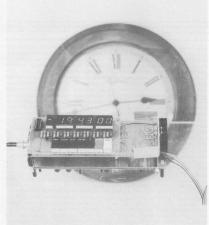
The choice of display is left to the constructors. A moving coil meter will be suitable and the offset voltage reading can often be eliminated by mechanically zeroing the meter. However, a standard multimeter of digital voltmeter will also do the trick, always remembering to subtract the offset voltage from the reading. If desired, the voltage range of the

output can be changed easily, since it is determined by the value of C2. As a rule of thumb, doubling the value of this capacitor will double the output voltage. The value given in the circuit diagram (2.2 nF) is a good choice: 20,000 r.pm. corresponds to 1 V at the output. The maximum value for C2 is 6n8.

# 6502 housekeeper

### A programmable time-clock

With all the digital clocks and watches available today, it is surprising that time-switches are often such crude affairs. Given the relatively low cost of microprocessor chips, it seems 'logical' to do the job properly! This article describes a sophisticated time-clock, based on a 6502 microprocessor. It can be used to control a multitude of household appliances, such as cookers, burglar alarms and house lighting. Incidentally, since it must keep track of the time to do its job, it can also provide a digital display of time, day and date. In other words it is also a digital clock . . .



A 6502 microprocessor keeps track of the time and day of the week. It also calculates the date, even bearing leap years in mind, so that it will remain accurate until 'February 29th 2100' ... (That is not a leap year, and most microprocessor-based 'perpetual calen-

ders' go wrong at that point!). Our electronic housekeeper is easily

programmed. It provides four control outputs for switching purposes. Three of these are intended for 'daily needs' - 'on' and 'off' times are set on a 24hours basis, and it is possible to select days of the week on which the sequence will not be executed. The times are accurate to within one minute. A fourth output is intended for a weekly cycle: ten 'on' and 'off' times are distributed over a seven-day period. The only restriction is that they must be set on a quarter-hourly basis.

The microprocessor checks the times entered; if a line seems to be switched off twice in succession, say, the 'housekeeper' will indicate this error immediately, during programming,

Obviously, this sort of thing requires an extensive program. A complete listing is included in this article, but we hope that enthusiasts will understand that we cannot explain it in detail . . . Describing the actual construction and operation of the time-clock takes up quite enough space as it is!

#### The hardware

Figure 1 contains the complete circuit diagram of the digital time-clock. At the heart of the circuit there is a 6502 CPU (IC1). The program for the clock and the switch functions is stored in a 2716 EPROM (IC3). The third large IC is a 6532 (IC2), which provides 16 I/O lines to control the display, scan the keys and read in the time data. In addition, the IC includes a timer (which generates seconds pulses) and another 128 bytes of RAM to store temporary data and the switch time entries. Apart from the 16 I/O lines to IC2, an additional four output lines are needed

for the different switching times. These are provided by the four-bit latch. IC4

The clock generator is shown at the lower left in the circuit diagram, The output from a 4 MHz crystal oscillator is divided by four to obtain the 1 MHz clock signal. This division is done by two flipflops, FF1 and FF2. Another alternative would have been to use a 1 MHz crystal in the first place, but the solution used here is a much cheaper way to obtain a 'clean' squarewaye

When the unit is switched on, a 'RES' signal initiates the reset procedure. This signal is generated by the circuit around T1, T2, N3 and N4. Initially, T1 will not conduct but T2 will, effectively shorting capacitor C7 and ensuring that the output of N3 is at logic zero. T1 starts to conduct when the rising supply voltage reaches 4.5 V. As a result, T2 is turned off and C7 starts to charge,

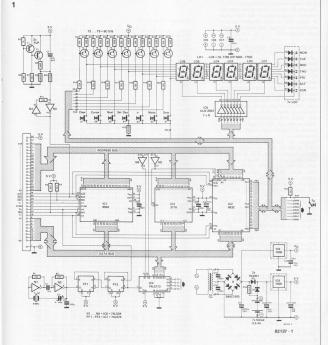


Figure 1. The circuit diagram of the programmable time clock. The 6502 CPU is situated at the centre of the circuit. The displays and their control unit are shown at the top and the power supply is located in the lower right-hand corner.

Due to the C7/R9 time constant, the output of N3 stays low for some time after the supply voltage has attained its nominal value. The circuit around N3 and N4 is included to 'sharpen up' the edges of the reset pulse. In passing, we can note that a reset pulse is also produced if the supply voltage briefly drops below the 4,5 V level for any reason, but this will be discussed later on.

One side of the six displays and 'days'

LEDs is connected to the I/O lines by means of the buffer/inverters in IC5 and the other is linked to the darlington transistors, T3...T9. The latter see to it that a constant current flows through the displays and the LEDs.

Two 5 V stabilisers, IC8 and IC9, produce the supply voltage. They both provide 5 V,IC9 feeding the LEDs and displays and IC8 looking after the rest of the circuit. This arrangement makes it easier to provide an emergency

(NICAD) battery supply. The batteries are placed at the input of IC8. During normal mains operation, a 'topping-up' current flows continuously through the batteries by way of resistor R35. In the event of a power failure, the batteries will feed the main circuit via D9 and IC8. At the same time, a very low current will pass through the displays (by way of R35 and IC9). This system reduces the current consumption from 0.8 to 0.25 A, so that the NICAD batteries used here will be able to stand in for about one and half hours.

in for about one and half hours.
The charge current flowing through the batteries is determined by the value of R35. This in turn depends on the transformer voltage and may be calculated as follows:

R35 = 
$$\frac{U_{C9} - 10}{20 \cdot 10^{-3}}$$
 = 50 U<sub>C9</sub> - 500  $\Omega$ 

During prolonged power cuts the batteries my be discharged to such batteries my be discharged to such voltage drops below 4.5 V. In that case, the reset circuit will introduce a reset to prevent errors in the program execution and failure of the display multiplexing unit (which might cause one of the displays to burn out!). The reset will also cause the programmed switching times to be lost. Fortunately, a power minutes!

Instead of NICADs, two ordinary 4.5 V batteris may be connected in series, in which case R35 is omitted. They will have to be replaced after a year or two, of course. Some readers may even consider this emergency supply totally superfluous, in which case the batteries, R35 and D9 may be left out altogether and D8 may be replaced by a wire link.

The address decoding system does not need to be complete and a simple circuit (using only two inverters) will suffice, because the memory range consists of only three blocks (IC2 . . IC4). The processor can deal with a total of

sists of only three blocks (102......(C4)). The processor can deal with a total of 64K memory, but what happens here is that the same 4K memory block is repeated throughout the range. The three blocks are decoded by address lines A10 and A11:

Memory is mapped as follows: \*000 \*400 \*800

(\* = don't care)

The chosen structure is by no means coincidental. The EPROM is at the top end of memory, because that is where the NMI, RESET and IRQ vectors have to be fetched, IC2, the 'RIOT' (this stands for RAM, I/O, TIMER.— a well — organised IC, despite its name), is situated at the other end of the range for two reasons:

Using the 6502 µP, 'zero page instructions (addresses 6000 ... 00FF) are only 2 bytes long. If similar instructions are required on any other page they will consist of three bytes. This is a highly effective way in which to economise on memory space.

Page 1 (Ø100 . . . Ø1FF) must contain

HEXDUMP: 0800,0FFF AA E8 95 3D DO F9 A9 0800: D8 0810: E0.47 DO F9 A9 00 85 04 0820: 0830: 60 AA 9A 58 00 EA EA 20 A5 87 00 A0 00 24 87 A2 0850: 28 F0 5C A5 80 10 F4 20 BC OB E8 20 8C 0B CA 0860: E3 A5 5F C9 59 DO 3F B5 4F D5 55 D0 1F CA 49 CA 10 F7 20 32 09 0870: 07 A0 06 20 9F 09 A2 05 B5 4F D5 05 B5 05 HF 05 0890: 08 61 A2 D8 86 9F 85 48 85 60 30 A1 A2 05 08A0: HE CA F9 A2 FF 86 60 20 32 09 30 90 04 A9 80 D0 02 A9 00 85 08B0: 0A 90 F3 E0 2B FO 02 E6 5D A6 38 CO 08D0: 28 F0 35 32 CO 41 FO 08FO: 49 FO 45 CO 46 CO 58 FO F8 D8 85 08E0 . 42 96 20 80 OB 98 BO 0900: 40 3E 08 A5 63 E9 10 9D 56 0910: 00 5D E6 SE D9 10 F1 4A 55 4A 4A CA F9 60 5B 1B 09 A2 OA A9 00 48 EO 02 DO 62 90 4B 89 09 10 F2 30 12 A5 20 68 A5 4E 85 67 A6 4C A9 38 0960: 89 09 85 E6 10 04 A9 85 45 60 FO OA 13 OB A6 5B A4 5C 60 A8 FO 06 C9 OF 0980: FO 60 A0 00 20 OB OA 49 60 DO 6R 0990: 20 24 DO 49 60 DO 64 99 49 00 20 0B 0A 09A0: 0B 0A 09B0: 99 4A OB OA 20 OB OA C9 08 D0 05 49 01 0900: 00 B9 29 30 41 C9 30 B9 4D 00 C9 08 49 FF 6A BO 90 nann. 09E0: 00 C9 02 D0 4E 00 29 FO 04 C9 A9 4B 00 OB OA 4B 00 6A OGFO: 20 OB OA 60 18 B5 FR 0400: DO 08 A9 48 E8 84 48 AQ 00 85 81 D8 95 64 C6 61 FO 08 A5 A9 85 9F DO 1B A9 0420: 9E A5 1D FO 07 A5 48 DO 03 49 09 85 82 20 E9 0A 68 40 85 A2 0A50: AA OA 88 DO OE B1 OE OA A4 0.4 OA 01 85 01 B0 1F C8 C8 A5 0A70: 08 A9 88 0A80: BO OA 90 A5 49 C8 D1 OF 90 OC BF 45 85 CO 09 DO E2 06 01 CA 10 0A90: 4C 90 F3 D5 0A 98 C5 no 1R OAAO: 90 OE BO OF B5 2A 29 29 03 OABO: BA 4A FO 04 A8 OA OA OACO: D9 OF 90 9F OA 60 8A 48 4A 3E 90 08 A II ha ha OADO: 04 AA B5 60 85 82 AA 60 OF 10 F8 A2 00 8A 09 OAEO: 02 E8 8A 4A A8 90 09 B9 48 00 li A OAFO: 84 C9 09 DO 1B A2 04 A9 02 85 82 FR OB00: 4A 03 40 85 4A 4A 4A 4A A8 B9 DB OF 0B20: 30 A4 1B FO 03 85 80 OB A5 21 C9 01 FO 07 25 0830 -1B D3 29 OF DB CA 86 OB B5 65 4C 2D 0B A5 21 F0 85 80 Oli 0B50: EO DO 86 OB A9 00 85 82 A9 BF 80 45 OB60: 09 80 6A 85 80 B0 F3 A5 80 09 A5 A2 FF 86 80 AA 60 AO 64 88 DO FD 60 20 3C 09 CQ OB80: 7F 9A 20 44 0E FA 20 13 0B E8 DF FO 06 C9 FD F8 20 C9 20 13 BF 13 OB OB E8 FO 13 A2 FO C9 OB90: OBCO: 4C AF OC 20 54 OE 4C 90 OB A2 FF 86 69 86 68 1D A9 02 C5 OB DO O2 86 66 A9 OBDO: 2A OA FO OBEO: OB FO 09 20 E6 OE E6 OB E6 OB 10 F1 20 OBFO: 9C OB 86 66 20 E6 OE E6 OB A9 14 C5 OB DO F5 20

ment is met by not connecting address lines A8 and A9 to IC2 (RIOT will therefore occupy pages 0...3). This means that the 128 bytes of RAM in IC2 are used for two different purposes. The lower section belongs to page zero (0000...0069) for storing data (intermediate results and switching times).

RAM for the 'stack'. This require-

whereas the rest acts as the stack in page 1 (016A...017F). Finally, the address range between RIOT and EPROM is used for the latch (IC4).

#### Construction and calibration

Figures 2 and 3 show the printed circuit boards for the digital time-clock. One board contains the displays, LEDs and keys and the other accommodates the processor, with its associated components and the power supply. The boards are designed to be mounted one top of the other, with the copper sides facing each other. Be careful when wring the boards and inserting them into a case. Some mounting holes are dilled through wide copper tracks. Use

OE OB 02 0B C5 A9 C5 20 1B C6 OE A5 OB OB OE 5B ocho. 54 OE A5 A5 0050: 20 D5 OA 08 F0 F0 02 28 84 1A E8 OB 0060: 1A 90 20 BO EA A5 69 5B 90 02 06 BO 68 C5 5C A9 CD 85 90 A5 OB 0080: A9 DA 85 68 A9 00000 FF AQ 85 OD OB OCAO: OA FO 06 20 50 OE OB OCBO -DO 86 02 OB 24 OC OCDO: A9 A9 1B FO A9 4A C5 OB 4A 90 OD00: 18 A9 00 OD10: E6 85 EQ A5 OD30: FO 85 69 OA OD40: FO 4D OF A5 90 OD50: 85 42 OD A9 85 4D OF 18 A5 OD60: 69 D8 60 DO 02 A9 0.0 4C OD70: OF E6 68 A5 68 29 OF OA DO A9 0080 : 68 FR OF OA OD90: 20 OE 4C OD A9 00 85 OF DO ODAO: FA 20 OF E8 ODBO: C9 EF 4F C9 DO 2A OA B6 DO B6 ODDO: OF E8 FA B6 OF E8 DF ODEO . FO FB ODFO: A9 DO DO 94 E6 A9 AO OE10: 20 OA B9 EA OF 85 66 0E20: FA B6 OF E8 B6 OF 0E30: OD 46 OC A5 DO EC 4C 96 OC FO D8 OA A9 OE40 - 66 A9 FF OA OA 0E50: A9 00 85 OB 89 2A C5 OE 16 OA E6 OB OB OB 60 CC 85 OA 0E70: OB OB AF OF 0E80: A5 OA OA OA OA OB 85 85 AA 05 85 68 1C 0E90: R6 A5 0B 6A 6A 90 OD A9 OEAO: 05 85 66 60 A9 OA OFBO: OB B5 A8 A8 4A 85 **B5** OECO: 29 B9 D5 F3 OA 8A 4A OA EA A5 88 OEEO: OA 2A FO OEFO: 85 AO A5 OB A5 OF00: 68 60 AO 00 A5 0B AA A5 69 OA OA OF10 - 68 0F20: 2A 95 AO 00 A9 38 6A 66 DO OF30: AA B5 3E 60 3E 29 FO 3E 98 OF50: DO FA 81 FA E8 OF60: DF DO BA E8 20 OE AQ 1A OB 18 OD A5 OFA0: 66 49 FF 85 66 OB 66 85 OFBO: 60 OFCO: A5 OFDO: 20 20 0C 13 45 0B 0B 66 D0 85 F8 E6 OD 13 FE 10 1A FF E6 OB FF OD A5 FF OFEO: 12 02 78 00 10 06 7B 2F FF BF DF OFFO: FD FE FF 00 15 30 45 FF FF FF D5 0F 00 08 16 0A

insulated spacers and screws here, as otherwise something may well go up in smoke!

The 'day' LEDs can best be flat rectangular types (such as HP 5082-4670). The days of the week can be indicated on the LEDs by means of transfer lettering. Different shaped LEDs may also be used and the days may be also be used to be a substantial to the days of the day

them with a saw

The two regulator ICs must be properly cooled. The back of the metal case can act as the heat sink if the regulators are mounted directly onto it, but mice insulation and washers must be used. The pins of the regulator ICs should be soldered onto the board, by the way, not wried. It is quite feasible to separate the control of the board, if desired, and mount it elsewhere in the case, and mount it elsewhere in the case.

The boards are connected so that both sets of PB0...PB6, PA0...PA6 and

PA7 pins are opposite each other. The connection points can then be linked with short lengths of wire. Then connect the three power supply connections on either board.

Once construction is complete you could insert all the ICs, connect the transformer to the mains and check whether everything is working satisfactorily, If something is wrong, it would be quite a problem to trace the error without a logic analyser. But there is another method, and a few hints on another method, and a few hints on coscilloscope or a multimeter can make all the difference.

Don't connect anything up for the moment, except for the stabilisers IC8 and IC9. Don't insert the other ICs into their sockets yet! The same applies to the batteries. Now check whether the output voltage of the two stabilisers is 5 V. Switch off the supply and insert IC6 and IC7, Switch on the power again and see whether there is a symmetrical 1 MHz squarewave at pin 8 of IC7. Readers who do not own an oscilloscope may use a multimeter instead and the auxiliary circuit in figure 4a. If the oscillator is working properly, the meter will indicate about 0 V. (A reasonably good frequency counter is needed to check the frequency: calibrate the oscillator with C2.)

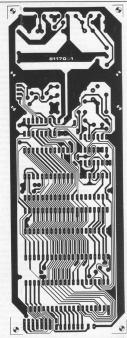
Now find out whether RES (pins 9 and 10 of IC6) is logic 1. If so, the code 'AA' is applied to the data bus by means of several wires and resistors, as shown in figure 4b. The indicated numbers refer to the connector pin numbers between IC1 and IC3 on the board.

Time to insert the 6502 (IC1) in its socket (turn the power off first!). After power up, a symmetrical squarewave with a frequency of 250 kHz should appear at A0 (connector pin 29), 125 kHz at A1, 62.5 kHz at A2, and so on down to 76 Hz at A15 B/W (connector pin 14) must remain high. If one of the above conditions is not fulfilled, first check whether AA is in fact being applied to the data bus. Again, this measurement does not require an oscilloscope and can be carried out by means of the auxiliary circuit in figure 4c. The circuit is connected to all consecutive pairs of address lines in turn: A15 and A14, A14 and A13, A13 and A12 . . . A1 and A0. Each time the meter should read either 0 V or 5 V. Any intermediate value indicates a fault. It is best to check whether there is a 7 Hz squarewave at A15 first by connecting the meter to it. The pointer will 'flutter' at this very low frequency (provided you are using a moving coil

The 'AA code' is now disconnected from the data bus. Remember, no soldering while IC1 is on the board! It will have to be removed from its socket each time. The next step is to mount the EPROM, IC3 (with the power off, of course!). Before switching on the power

meter). Then check all the address line

pairs with the auxiliary circuit.



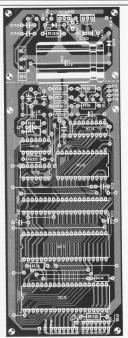


Figure 2. The main printed circuit board. This accommodates the entire microprocessor unit. The power supply section may be separated, if necessary.

#### Parts list

2

Resistors: R1,R2,R7 = 2k2 R3 R4 R12 = 3k3

R5 = 1 k R6 = 5k6

R6 = 5k6 R8 = 56 Ω R9 = 560 Ω

 $R10 = 470 \Omega$  R11 = 15 k  $R13 = 220 \Omega$  $R14 \dots R20 = 12 k$ 

R14 . . . R20 = 12 k R21 . . . R27 = 10 k R28 . . . R34 = 10 Ω R35 = 120 Ω Capacitors: C1 = 10 n (cer.) C2 = 4 . . . 40 p trimmer

C3 = 150 p C4,C5,C6,C13,C14 = 100 n C7 = 47 µ/6.3 V

C8,C11,C12 =  $10 \mu/10 V$  (tant.) C9 =  $2200 \mu/25 V$ C10 =  $10 \mu/25 V$  (tant.)

Semiconductors: T1,T2 = TUP T3 . . . T9 = BC 516 IC1 = 6502 IC2 = 6532 IC3 = 2716 IC4 = 74LS173 IC5 = ULN 2003 IC6 = 74LS04 IC7 = 74LS74

IC7 = 74LS74 IC8,IC9 = 7805 D1 . . . D7 = LED red see text

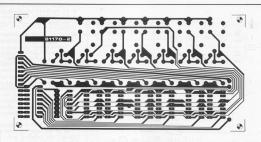
see text D8,D9 = 1N4001 B = B40C1500 bridge rectifier LD1 . . . LD6 = DL 7760

#### (HP 5082-7760) Miscellaneous:

Tr = 10 V/1,5 A mains transformer

S1 . . . S7 = digitast X = 4 MHz crystal





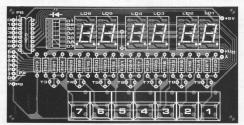


Figure 3. The display board contains the displays, LEDs, control electronics and pushbutton keys.

supply again, link pin 26 of the connector (NMI) to pin 36 (A7). After power

(A3... A0 are not stable)

Furthermore, pin 20 of IC3 should be constantly low. If something is wrong, either the EPROM was not correctly programmed or N5 is not inverting the

signal. If everything is O.K. so far, pull out the mains plug for the last time, remove the connection between NMI and A7 and insert the remaining ICs. The clock should start to count from 00 00 01 as soon as the circuit is switched on.

Calibrating the crystal oscillator accurately is not an easy job. As mentioned earlier, the oscillator can be adjusted with C2, with a quality frequency meter connected to pin 8 of IC7. However, as few readers will be fortunate enough to

own a really accurate frequency meter, here is an alternative method. It can be just as accurate, but it is rather more time-consuming...

First set the trimmer capacitor C2 in its centre position. Switch on a radio and wait for the time signal on the hour (1100, 1200, etc.). Synchronise the clock on the sixth 'pip' of the radio time signal and press the start button. Let the clock run 'on its own steam' for several hours and then compare it to 'real time' again. Check whether the cocillator is 'fast' or 'slow' and 'readjust it it the C2, it necessary. By repeating period of a few days, if necessary) readers will be absolutely sure the cocillator is 'accurately calibrated.

#### Programming the timer

A pushbutton switch (SA) is connected between the input and ground to start the time entry routine. Operation is as follows. After power up, the clock starts to count from 00 00 01. The clock is

stopped by depressing SA. The week/ day LED then flashes. The desired day of the week may be selected with the > pushbutton (S3). Then the CURSOR key is operated (S6) and the tens/hour display starts to flash. The hours may be set by depressing > several times. The hours, minutes and seconds are all dealt with in the same manner. Once the 'second' units have been entered and the CURSOR key is operated again, the date will appear on the display. The same procedure is followed to enter the correct data, starting with the day and ending with the year (from left to right, in other words). Take care not to program an impossible date, as the clock might feel inclined to misbehave. After the year entry press the CURSOR key again. The time will then reappear on the display but no LEDs will flash, Now press the MODE key (S2) and the clock will start one second later, Readjust the time or date setting with the SA key, if necessary. By the way, SA doesn't have any effect unless the clock is 'ticking'!

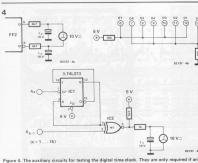


Figure 4. The auxiliary circuits for testing the digital time clock. They are only required in a oscilloscope is not available.

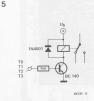


Figure 5. This tiny 'interface' enables outputs T0...T3 to switch mains-powered equipment on and off.

Nothing happens if it is operated during the switch time entry routine, which is described below.

The four control outputs may be connected to any device that needs to be switched on or off at a specific time by means of a relay or a triac circuit. Outputs TO...T2 can each program four switch times within 24 hours. In addition, the day of the week may be entered on which these switch times are to be processed. Every day at 00.00 hours the outputs TO...T3 to increase witchin 24 hours the outputs TO...T3 to increase witching interval between 'on' and 'off') is one migrate.

The fourth output, T3, can be programmed for a weekly cycle. It provides 10 'on' and 10 'off' times that can be set at fifteen-minute intervals. This line is automatically reset at the beginning of every week (at 00.00 hours on Monday morning).



The switch functions are as follows:

S1, the DATE key, displays the date.

- S2, The MODE key, selects between the time display and the switch time
- entry.
   S3, the > key, increments the value on display that is indicated by a flashing cursor.
- S4, the SET DAY key, serves to program the days of the week.
- S5, the NEXT key, shows the next switching time on the display.
- S6, the CURSOR key, moves the cursor from left to right across the display (but not the right-hand digit: that indicates whether an 'on' and 'off' time is involved). The display selected by the cursor flashes to indicate that it may be altered, if necessary, with the > key.
   S7, the CLEAR key, deletes some or
- S7, the CLEAR key, deletes some or all of the switching times on a particular line (starting with the time currently on display).

As mentioned above, the right-hand display indicates whether the switching time shown refers to 'on' or' 'of'. 'On' is represented by a '1' and 'off' by a '0'. Its neighbour shows the line number (0, 1, 2 or 3). A program example is included in this article to illustrate how the various keys work, and to give an idea of the facilities.

A return to the normal time display routine causes T0... 73 to be modified according to the entered switching times. This occurs exactly one second after every minute period. During programming of the switching times, the outputs remain unchanged.

One final point. If an 'off' time is proprogrammed and this turns out to precede the 'on' entry, depressing the MODE key will cause an ERROR message to appear on the display for a few seconds, followed by the first time that is programmed for the line where the error occurs. No return can be made to the time display. First the error must be corrected, after which the MODE key is operated to switch the processor back to time display.

## Switching mains-powered equipment

Readers who wish to switch mainspowered equipment 'on' and 'off' with the aid of the time switch require a small interface for each of the four switch outputs. Figure 5 provides a simple circuit for this purpose. The switch output controls a transistor by way of a resistor. The relay can then switch a device on and off. How much power may be switched depends on the type of relay. For the transistor shown, the relay current should not exceed 100 mA. If 12 V relays are to be used they may be connected directly to the time clock's power supply (across C9). This method ensures that the circuit is electrically isolated from the mains voltage. A solid state relay is of course equally suitable.

#### Program example

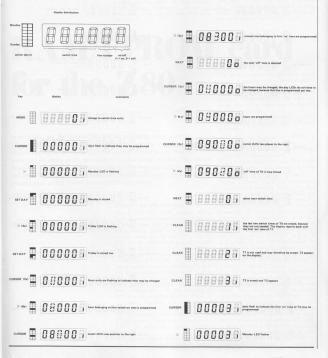
Switching times to be programmed: line TO: switch on at 08.30 on Monday and Friday switch off at 09.02

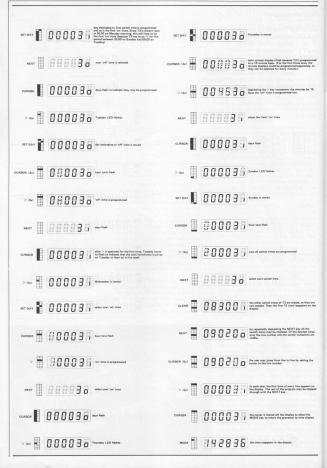
line T1: constantly '0'

line T2: constantly '0'

line T3: switch on at 20.00 on Sunday switch off at 08.00 on Tuesday switch on at 10.00 on Wednesday switch off at 00.45 on Thursday indicates a day LED is unlit
indicates a day LED is lit

S indicates a display in flushing





Memory cards are basically birds of a feather. They all contain memory ICs, BUS buffers and a control circuit. The latter, however, does tend to vary from one system to another. The RAM/ EPROM card described in the September '80 issue was originally designed for use with the SC/MP and 6502 systems, but after a couple of alterations it can be run on the Z80 as well. This involves changing the printed circuit board by breaking 9 tracks and then inserting 7 new wire links. No new components are required. In other words, it is just a 'cut and shunt' exercise.

Figures 1 and 2 show the changes that need to be made to the lower and component overlay sides of the printed circuit board, respectively. As can be seen, very little cutting and linking is required.

memory access and refresh cycles. During normal memory access the CPU starts by outputting addresses. After a short period, the MREQ signal is generated. This is accompanied by the RD strobe during a read cycle, in which case both signals will be synchronous. After the two signals the CPU stops reading

Things are different in the write cycle where the CPU produces the MREQ signal and simultaneously transmits the output data to the data bus. But the WD line is not enabled until after a brief interval to allow the active edge of the strobe to be used for data storage (provided the system is buffered in such a way that the data bus really does pass data to memory before the WD strobe arrives!). The WD signal is disabled at the same time as the MREQ signal.

# RAM/EPROM card for the Z80

A. Seul

In principle, the RAM/EPROM card (as published in the Elektor September '80 issue) may be connected to a variety of microprocessors. One or two minor alterations to the control circuit are all that is necessary, in many cases, to match it to a particular system. This article describes the changes needed in order to interface the card to the Z80and the Z80-A CPU, in particular, as this is introduced elsewhere in the present issue as the 'brain' behind the Polyformant.

#### Reasons for the changes

The SC/MP and 6502 systems define both the address range and the direction in which the data transfer is to take place during either the read or write strobe produced by the CPU. In the Z80, on the other hand, a valid address may be output on three separate occasions: during normal memory access, when one of the 256 I/O addresses is being accessed and in the case of memory access during a refresh cycle. Taking into account the additional possibility of a non-valid address, only two CPU lines would seem to be required to define every possible address status. In actual fact, however, the Z80 processor uses three lines:

MREQ to access memory locations; IORQ to access peripheral devices and RFSH to access and refresh dynamic

RAMs. Let's forget about IORQ for the moment and see what happens in normal The memory card may not be accessed during a refresh cycle. What happens here is that the refresh line is enabled first, after which the MREQ signal is strobed, RD and WD are not used, because the CPU ignores data during this particular process.

The control circuit of a memory device operates according to the following parameters:

- 1. Memory is accessed if MREQ is
- enabled and RFSH is disabled. 2. Data must be applied to RAM before the WD strobe is enabled.
- Data must only enter the BUS while RD is enabled and memory is being accessed.

Figure 3 shows the circuit diagram of the modified memory board. The first parameter is met by linking MREQ and RFSH by way of N6 and N7. Pin 8 of N7 will then only go low, if the CPU addresses a memory location. The memory card should only react to a memory access if the relevant memory range is being selected. This is achieved by connecting pin 8 of N7 to pins 18 and 19 of IC5 (the 74154 decoder). Its outputs activate the CS decoder IC6 and IC7 by way of N1 and N2. In addition, the output of N5 produces an active high CARD SELECT signal.

The second requirement is fulfilled by making sure the card transfers data from the BUS to memory during its quiescent state. Thus, data will also be applied upon the arrival of the WD signal.

The 6502 processor implements the WD signal instead of its RD counterpart to transfer data to the data bus when memory is being accessed and the WD signal is disabled. In a Z-80 system, this would go hopelessly wrong: during a write cycle the CARD SELECT signal will precede the WD strobe. The original cir1b

Figure 1a. The circles indicate which tracks on the lower side of the printed circuit board need to be broken.

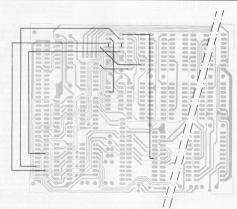
cuit 'notices' the signals and starts a read cycle. It will therefore transfer RAM data to the BUS until the write pulse WD appears. On the one hand, this prevents data from being applied to RAM upon the arrival of the WD strobe (second parameter) and on the other. the data bus is already being driven by the CPU buffers, as the CPU control circuit has acknowledged the write cycle. Bi-directional transfer is strictly forbidden in the BUS. Depending on which drivers are being operated, current peaks will be produced on the +5 V and GND lines, which could well make the system collapse.

N3), and used to control the direction of data transfer in the data bus buffers. N4 serves to buffer the WE line, which has the arduous task of driving 16 ICs.

Inverters N6 and N8 and NAND gate N7 required for the modification are already included on the printed circuit board in IC29 (74LS00). In the original circuit, the unused inouts are either high

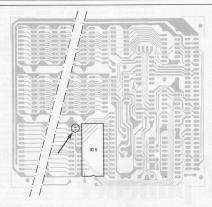
To avoid these problems, the  $\overline{\text{RD}}$  signal is inverted by way of N8 (and linked to the CARD SELECT signal by way of

Inverters NB and NB and NAND gate N7 required for the modification are already included on the printed circuit board in 1C28 (74LS00). In the original board in 1C28 (74LS00) are replaced to a void crostalk to active gates. These connections should now be replaced by the links indicated in figures been made, the RAM/EPROM card will be ready for use with the 280.



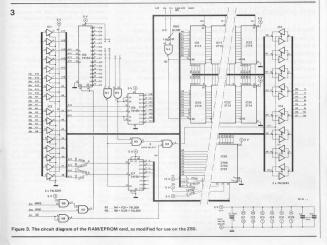
82134-2

2



82134-3

Figure 2. Only one track needs to be broken on the component overlay side.



Junior Computer owners regularly send us programs that they have written for 'their' machine and Elektor's editorial staff dutifully try them all out and 'unravel' them with the disassembler. Unfortunately, the task is not always a rewarding one and occasionally the work resembles that of a pathology lab. Nevertheless, it is gratifying to receive so many sparks of initiative! Any attempt in this direction automatically calls for a disassembler, but that is by no means the only reason for having a 'software cruncher', Used in combination with the editor and assembler the disassembler enables operators both to write their own programs and decode those gleaned from friends or magazines.

# software cruncher puncher

disassemble Junior Computer software and program 2716 EPROMs

Whereas developing one's own software is often like taking a leap in the dark, analysing other people's programs can sometimes be quite a revelation. In either case a disassembler is called for such as the one described here. In addition, it is a useful aid towards 'BASIC' conversion. And, as the software cruncher is stored in 2716 EPROM. why not include an EPROM programming program, (to use up the remaining EPROM space), together with the EPROM hardware published in January?



#### The details

The software cruncher is stored in 2716 EPROM. The software occupies the address range \$F800 ... \$FFFF. The EPROM may either be mounted on a RAM/EPROM card or on the mini EPROM card published in the April issue. Locations \$F800 ... \$FDD9 store the actual disassembler.

\$FDDA . . . \$FFF9 contain the 'EPROM PROGRAMMING UTILITIES' (which are described later on in the article) and \$FFFA ... \$FFFF include the vector data with which JC owners are already familiar.

ware 'cruncher' is shown in Table 1. After initiation (enter the start address \$FC4E through PM!) the computer reports back by defining the relevant function keys. The D key is operated to enter two addresses which 'cordon off' the memory range that is to be

disassembled (ending in CR). In the

example given in Table 1 this comprises \$0200 ... \$022F. Note that the end address must be entered and that the 'end address + 1' rule does not apply here.

This is followed by the message 'L, P, SP?'. By depressing the L key the operator can disassemble the entire memory range 'in one go'. The P key, on the other hand, does this in blocks of 15 instructions (a full TV screen, the top line being the last one to be printed before P was operated) and the space bar SP allows each instruction to be disassembled in turn and is therefore the slowest method.

The 'crunched' program in Table 1 gives an idea of the type of informa-tion that is printed. Table 2 shows the Hex dump of the disassembler. First of all, the address and the op code of the instruction are displayed followed by the byte(s) contained in the instruction. Then the mnemonics (the instruction 'shorthand') are printed preceded by several spaces. Wherever relevant, the line ends with the operand data. The displacements involved in conditional jump instructions are 'translated', so to speak, as the 'jump address'.

Data that is not acknowledged to be the op code of an instruction has the mnemonic consisting of three American AT symbols assigned to it (see address 021E, for example). Such data is one byte long. Note that FF is not acknowledged as a label op code.

Then R is operated and the program returns to PM. What could be easier?

#### Table 1.

FC4E			
FC4F	AGR		

VALID COMMANDS: A D H L P R SP

DISASSEMBLE: 200, 22F L, P, SP?

L			
0200	A9	00	LDA#\$00
0202	AD	01 02	LDA \$0201
0205	A5	03	LDA \$03
0207	A1	04	LDA (\$04,X)
0209	B1	05	LDA (\$05),Y
020B	B5	06	LDA \$06,X
020D	BD	07 08	LDA \$0807,X
0210	B9	09 0A	LDA \$0A09,Y
0213	B6	0B	LDX \$0B,Y
0215	20	0C 0D	JSR \$0D0C
0218	4C	OE OF	JMP \$0F0E
021B	6C	10 11	JMP (\$1110)
021E	77		@@@

BRK 0220 00 0221 00 BRK 0222 CA DEX 0223 CR 0224 E8 INX

0225 OA ASL A 0226 FO BEQ \$023A 0228 DO BNE \$0228 022A BO 34 BCS \$0260 022C 90 EE BCC \$021C

022F FA 022F 00 BRK

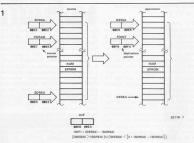


Figure 1. The memory ranges involved in the EPRUTL routine, Operating the M, R, V or F key causes the CURAD and POINT pointers to move through every location from SORSA and DESSA to SOREA and DESEA, respectively.

As for the H and A keys, depressing H is equivalent to operating M during PM and A represents 'ASCII dump'. Thus, a hex dump is printed after two address entries followed by CR (see table 21. The A key causes a hex dump to be printed showing the ASCII code the \$20 ... SYE range. In the case of data outside this range, a space appears. This feature allows data, such as computer messages that need printing, to be located swiftly. Once readers manage to crunch the disassembler messages that the is riddled with such messages.

#### Not only, but also . . .

The printing operation of the dump or listing may be interrupted by depressing the BRK key. The BRK jump vector leads the 6502  $\mu$ P to a central point in the program where it waits for a (new) key to be operated.

When two addresses are entered for the purpose of defining a listing or dump, the second address must be higher than the first. Otherwise, the two addresses will have to be re-entered, only this time in the right order please!

As well as storing data in much used memory locations in pages 60 and 1A, the software cruncher must dispose of \$800 ft 0...\$0027.\$0028 must now also be added to accommodate the extra software. Operators must be careful not to use these memory locations for the program they wish to 'sort out'.

#### Software puncher

As mentioned earlier, now that we have the necessary hardware (Elektor January 1982), a start can be made on loading RAM or EPROM software into 2716s. The program is started by

way of PM at address \$FDDA, After initialisation, the name of the program is printed along with a list of valid keys. Then the parameter key, P, should be depressed so as to define the address range by entering three addresses, as shown in figure 1. First of all, the FIRST, LAST SOURCE ADDRESS must be specified, in other words, the SORSA and SOREA addresses at either end of the data block that is to be stored or relocated. Make sure SOREA has a higher number than SORSA, as otherwise the entry procedure (first address - comma - last address - CR) will have to be repeated. Next, enter the 'FIRST DESTINATION ADDRESS'. This is known as DESSA and determines the location of the first address belonging to the data being programmed or moved. (Enter the first address followed by CR.)

The following key functions are valid:
The M (MOVE) key ensures that the
SORSA...SOREA data block is stored
or relocated (provided the EPROM

SON MODITAL MANUAL PROMOTION TO THE PROMOTION OF T

The F (FF check) key enables the operator to check whether locations DESSA ... DESSA + n - 1 contain FF for represents the number of memory locations in the data block being programmed. If 8 to, data may be stored in that particular range. The address and contents of any memory locations that contents of any memory locations that of the contents of any memory locations that of the contents of any memory locations that the contents of any memory locations have been run through, 70ATA COMPARED appears.

Table 2. Hex dump of the cruncher.

The R (RELOCATE) key. All the absolute addresses within the data block SORSA... SOREA are adapted to the new situation brought about by moving or programming a data block. The new address is determined by the contents of DIF (see figure 1). At the end of the procedure, 'RELOCATED' is printed. The R key function is not needed while relocatable software is being stored (without any internal JMPs and subroutines) or if the contents of one EPROM are being loaded into another. In order to copy RAM data into EPROM, depress R, then M. But to store EPROM data into RAM, depress M followed by R.

The V (VERIFY) key. This compares the original data block and its relocated version, byte by byte. Whenever an error crops up, the offending location is printed along with its address and contents. The operation signs off with the 'DATA COMPARED' message.

The B (BACK) key introduces a return to PM whenever the computer is ready or the operator wishes to disassemble a relocated/programmed data block (to verify the R key routine).

The ST Fey CST/MIII on the main keyboard allows a strum to take place from PM to EPRUTL, like a warm star entry. Then XXXX <= AD =< YYYY TO >= 2ZZZ' appears, where XXXX stands for the FIRST SOURCE AD-DRESS, YYYY stands for the LAST SOURCE ADDRESS and ZZZZ stands for the FIRST DESTINATION AD-DRESS.

By the way, ST may also be operated during EPRUTL to print the three address parameters and their interim status during an operation. This is extremely useful, as sometimes the parameters need to be temporarily altered. At the same time, the operator is reminded of what was entered three 'screenfuls' before.

How to prevent programs from going 'off the rails'

1. The EPROM programmer must be connected to the bus board. The card is addressed in the normal manner during programming. This means that a "FIRST DESTINATION ADDRESS" (\$2000 or higher) must be entered for reasons described in Book 3. But this does not imply that any EPROM data located below \$2000 in the memory map, such as the main board monitor and the TM and PM software, is excluded. Details are provided in point 3.

2. Using the S3... S6 switches, a 4K address block must be selected that does not coincide with any existing data blocks. Otherwise double addressing occurs. If necessary, remove one or two memory cards from the bus board for the time being. Remember that the first two 4K blocks are also out of bounds (see point 1).

3. The FIRST DESTINATION AD-DRESS entered just before the start of the program must be located within the selected 4K block (see point 2). This address does not necessarily have to be the ultimate first address (it may be modified later). Right now we intend to load data into the EPROM on the programmer, byte by byte, with the aid of the M key. But take heed! If any absolute addresses need to be altered. start by entering the real FIRST DESTI-NATION ADDRESS using the Pkey. (Then depress R and P again, followed by the first address of the EPROM programmer.) Finally, operate M.

4. S2 on the EPROM programmer is not switched 'on' until just before the actual programming sequence (with the M key). During programming LED D9 lights and remains lift for the entire process. (About 20 bytes are loaded per second, so it takes quite a while). S2 should be switched off as soon as D9 has gone out and 'DATA MOVED'

appears on the screen!
5, 2716 and 2732 EPROMs have one

thing in common: they do not enjoy being exposed to the full brunt of the 25 V programming voltage without having the comforting protection of the 5 V supply voltage. The circuit in figure 2 is added to the EPROM programmer hardware "to cushion the blow".

6. To find out whether a 2716 IC is truly empty, access a 4K block on the EPROM programmer; select a FIRST DESTINATION ADDRESS that either corresponds to the first address in the range or to one 2048 locations further on, and enter any 2K data block. Now depress the F key.

7. Whenever EPROM software needs to

be duplicated, store the 'master' version on a RAM/EPROM card, (unless it is a system EPROM). Insert the (presumably) empty EPROM on the programmer board. Then follow the instructions given in points 3 and 4. After a short while the data 'transfusion' should be complete.

8. Loading EPROM software into RAM is no problem and may come in handy whenever system programs are to be stored on cassette or the contents of an EPROM are to be changed. First copy the data (using the M key) and then relocate it (with the R key), and ator to check which locations have been altered as a result of the R key routine.

9. When using the R key, watch out for look-up tables and 'stringst' Data such as '20 41.54' is ambiguous, for it may either be the ASCII code for 'uAT', or stand for JSR-\$54411 If 54 constitutes an ADH within the data block being programmed [\$2000 ...\$\$FFF on the dynamic RAM cardy the channes are, operating the R key will cause the 54 to be delethed. That is why it is a good idea to check the location of such ables beforehand, and makes sure they the summer of the summe

10. Å special program, as described in the January article on EPROM software, would be needed to store data in the 'step' mode using the original monitor routine. Fortunately, this is no longer necessary, thanks to the PM routine, Just enter the EPROM proting the programmed of the EPROM programmer is ready for programmer is ready for programmer is ready for programming, as indicated in point 4.

Although very few keys are needed to program EPROMs, operators will discover that they offer a surprisingly versatile repertoire.

2

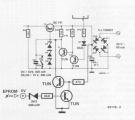


Figure 2. This circuit is added to the EPROM programmer to prevent the EPROM being loaded from becoming a fried oth pit 52 is inadvertently switched on before the EPROM programmer power supply is connected up. A common mains switch does not provide a 100% guarantee!

# market

#### 'Small business' printer

The latest family of bi-directional logic seeking dot matrix printers from Centronics Ltd — the 150 series — is now being stocked by Bytech Limited. These versatile 150 character per second machines are available for either 10-inch or 15-inch paper widths, and have snap-on tractors to handle roll, cut-sheet or fan-fold paper.



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Bytech Limited, Unit 57, Suttons Ind. Park, London Road, Earley, Reading, Berks. Telephone: 0734-61031

(2348 M)



a time access control for oscilloscopes or pen recorders.

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(2345 M)

## Combined function, sweep and pulse generator

House of Instruments announce the WG 230 from Trio, which combines the capabilities of a function, sweep and pulse generator in one high quality compact unit. The wallity compact unit. The wallity compact unit. The will inser divided, high resolution main dial from 20 Hz to 200 kHz, with an auxiliary control covering the range 2 Hz to 200 kHz.

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(2341 M)

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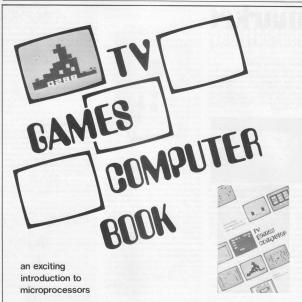
N.S.F. Limited, Keighley,

West Yorkshire BD21 5EF. Telephone: 0535-67144

(2336 M)



5-58 - elektor may 1982 advertisement



The first acquaintance with microprocessors can be rather frightening. You are not only confronted with a large and complex circuit, but also with a new language: "bytes," ("PC", "AAM", "peripherals' and so on, Worse still, the finished article is a miniature computer and so you have to think up some sufficiently challenging things for it to dol This book provides a different — and, in many ways, easier — approach.

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